

Computational Vision

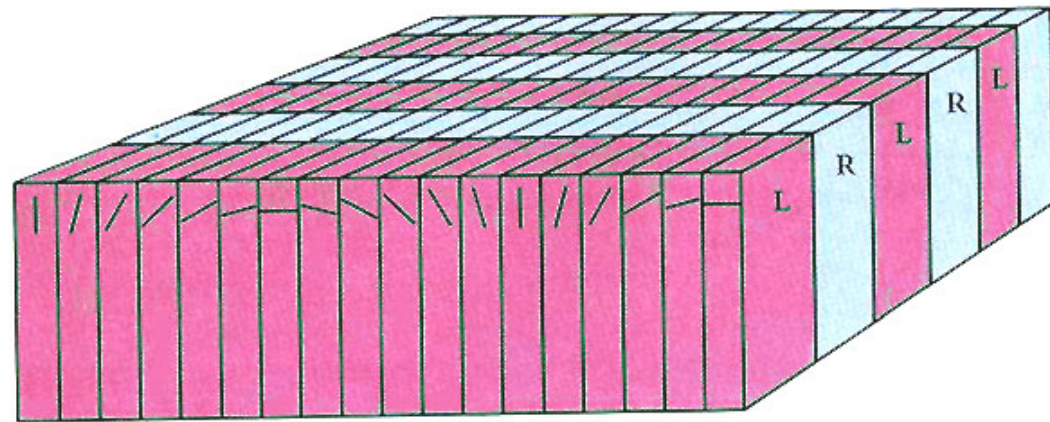
Primary visual cortex

- Orientation selectivity
- Spatial frequency
- Color opponency
- Normalization



Computing with V1

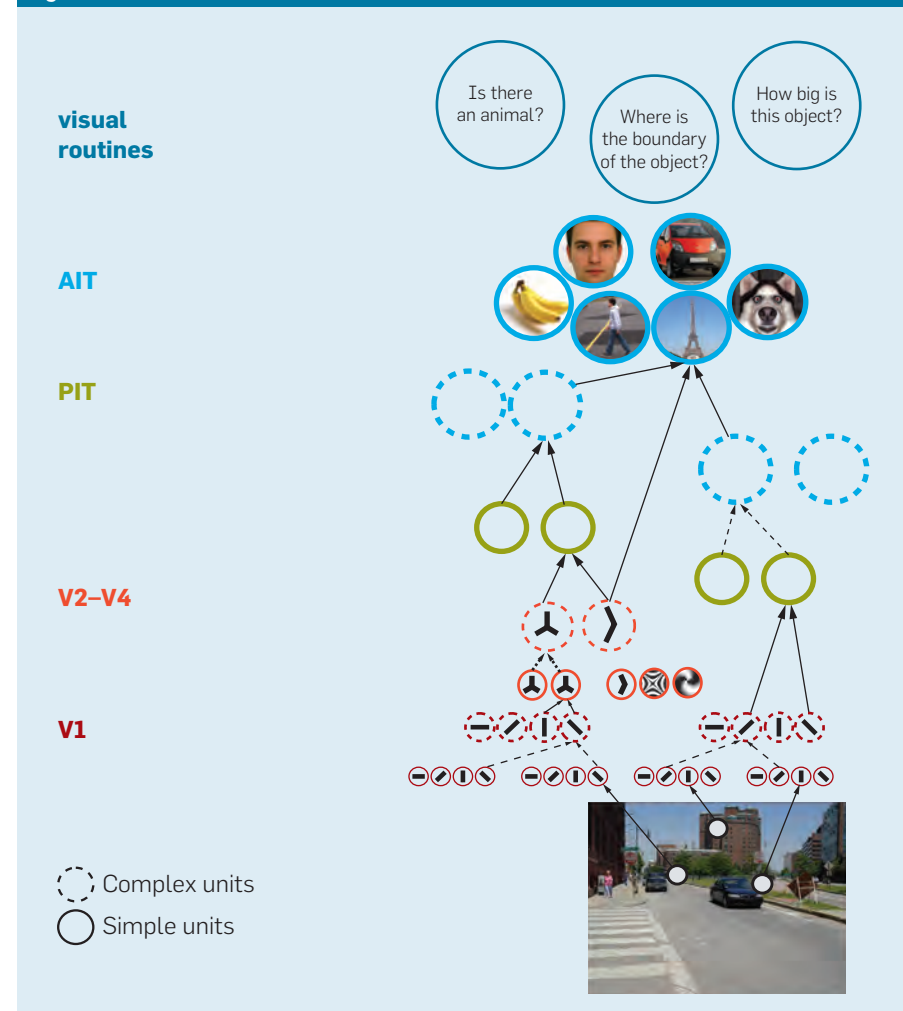
Gabor filters



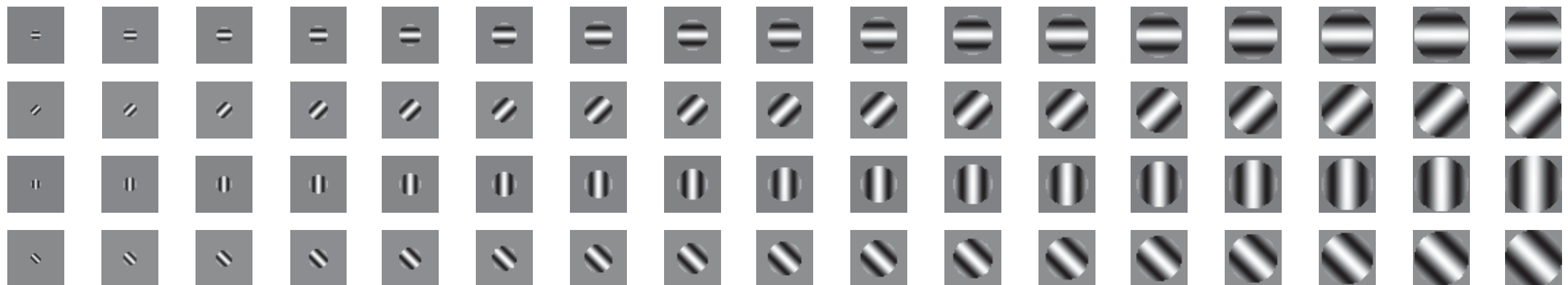
Orientation and ocular dominance columns

Figure 23. The ice-cube model of the cortex. It illustrates how the cortex is divided, at the same time, into two kinds of slabs, one set of ocular dominance (left and right) and one set for orientation. The model should not be taken literally: Neither set is as regular as this, and the orientation slabs especially are far from parallel or straight.

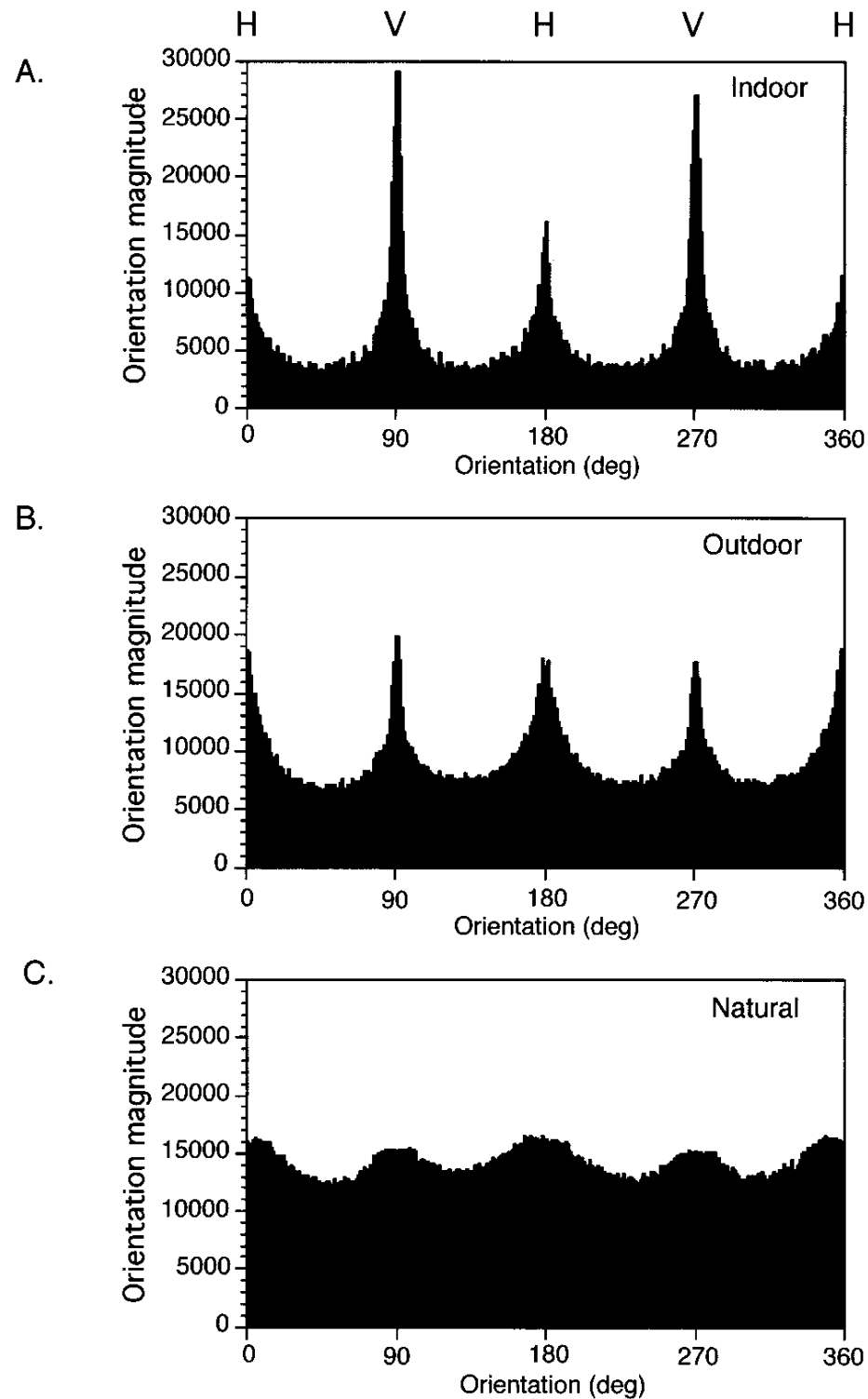
Figure 2. Hierarchical feedforward models of the visual cortex.



Gabor filters at multiple phases (one phase shown), orientations and spatial frequencies/scales (parameters derived from available experimental data)



Structure in natural images



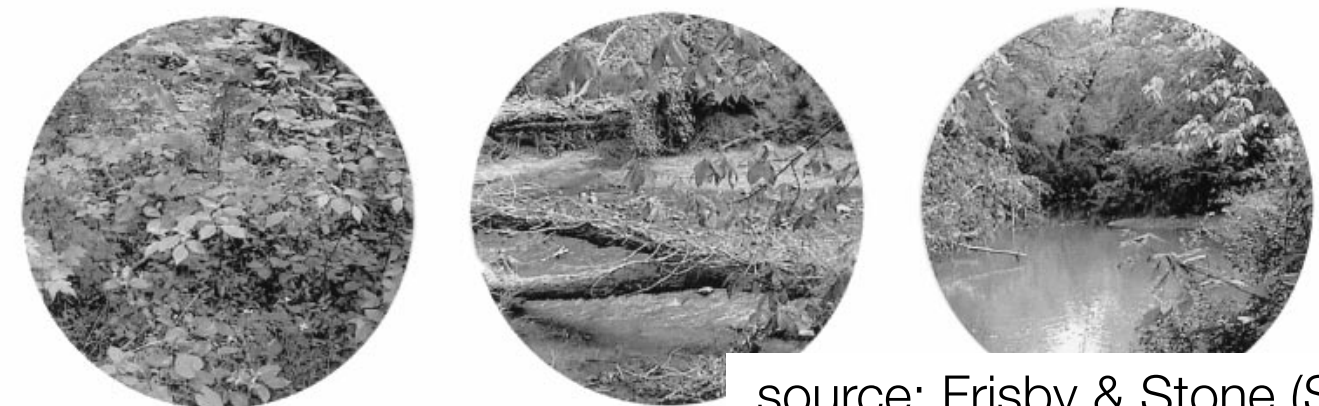
A. Indoor scenes



B. Outdoor scenes

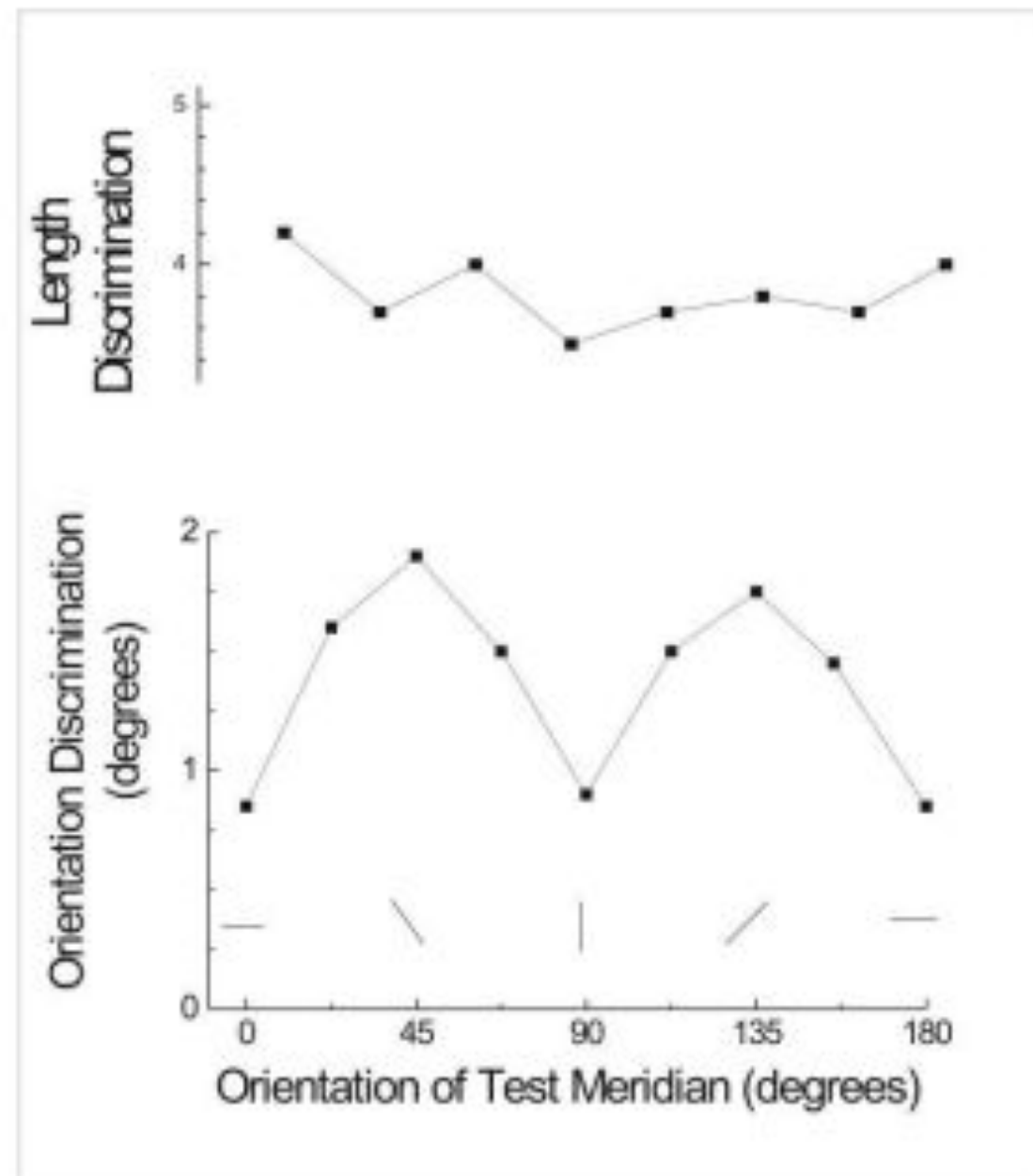


C. Natural scenes



source: Frisby & Stone (Seeing)

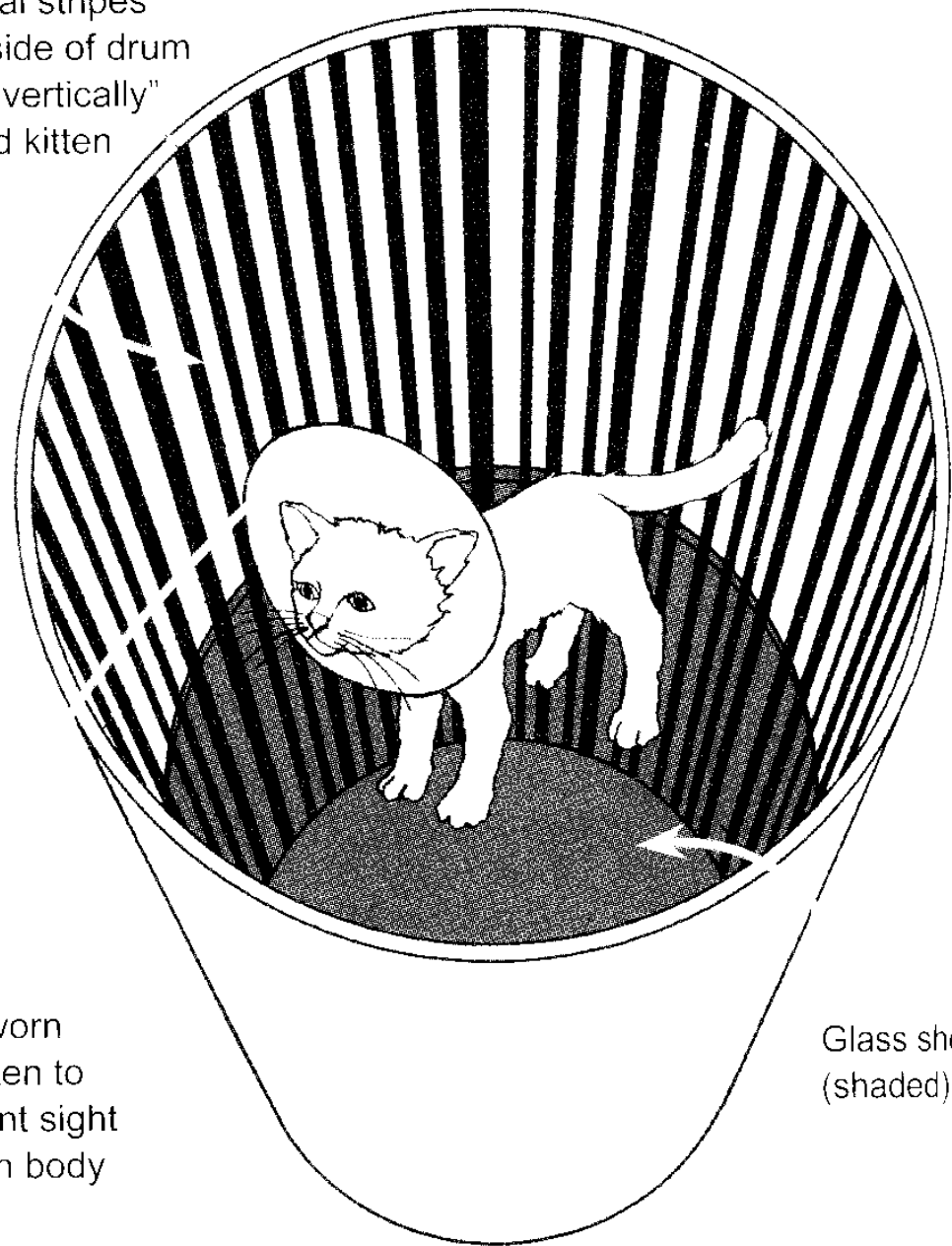
The oblique effect



Rearing experiments

Vertical stripes
on inside of drum
for a "vertically"
reared kitten

a

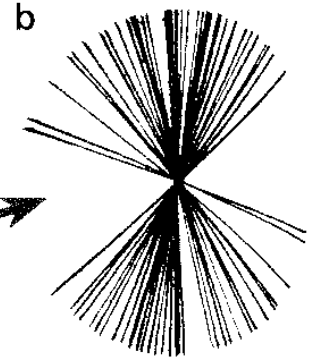


Ruff worn
by kitten to
prevent sight
of own body

Glass shelf
(shaded)

Missing horizontally-tuned
cells usually found in a
normally reared kitten

b



Natural image statistics cont'd

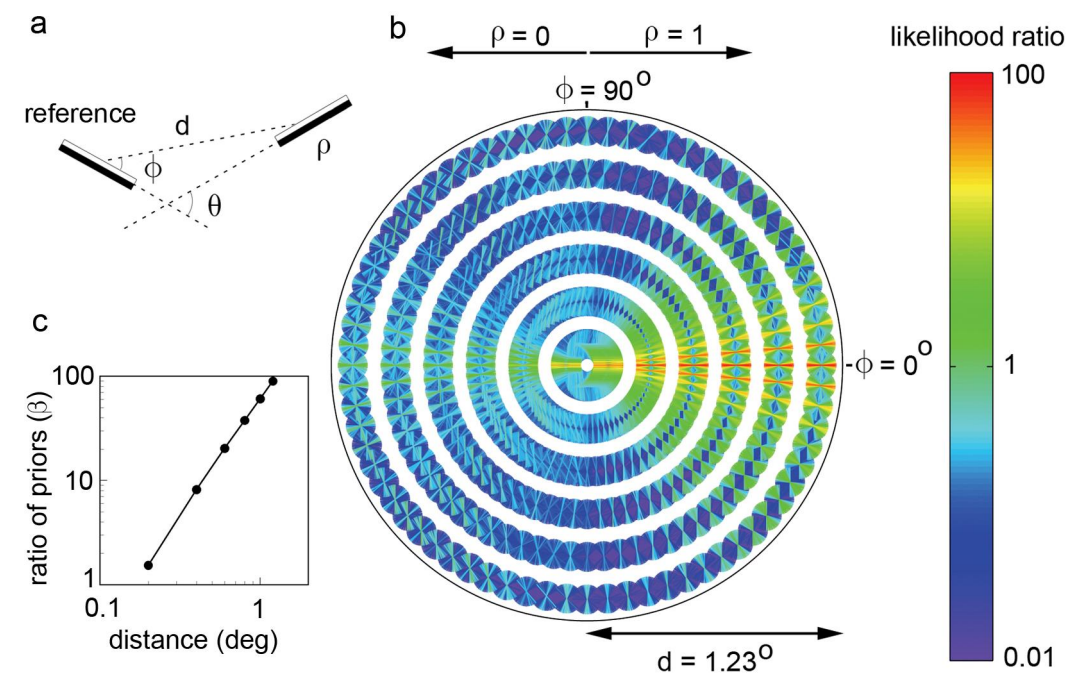
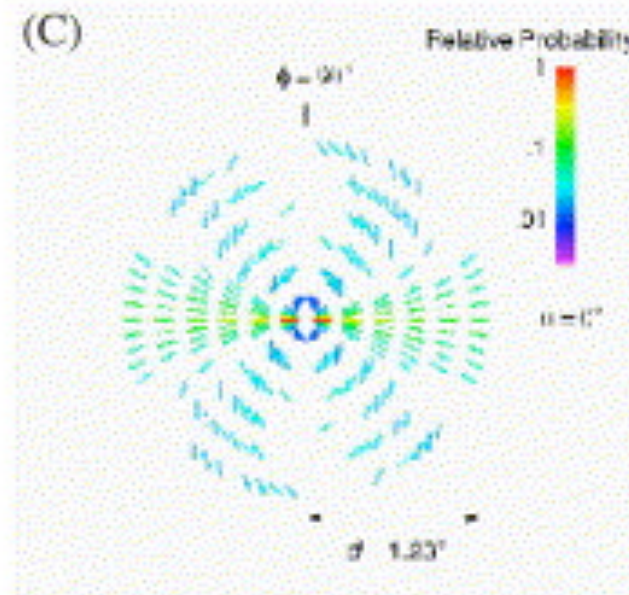
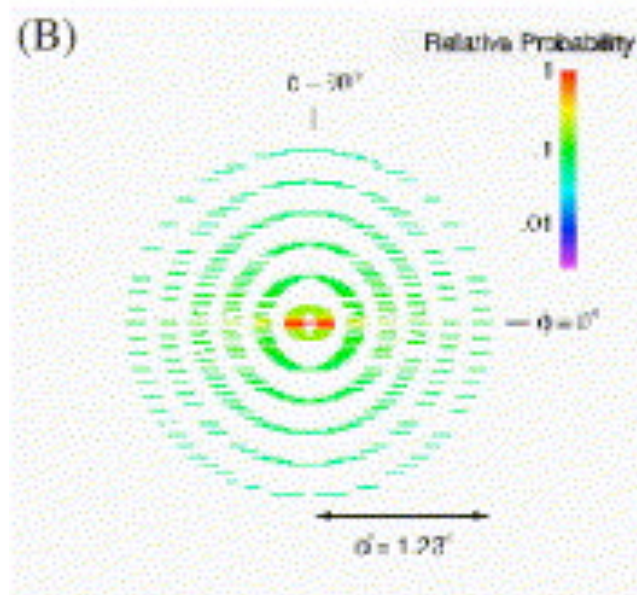
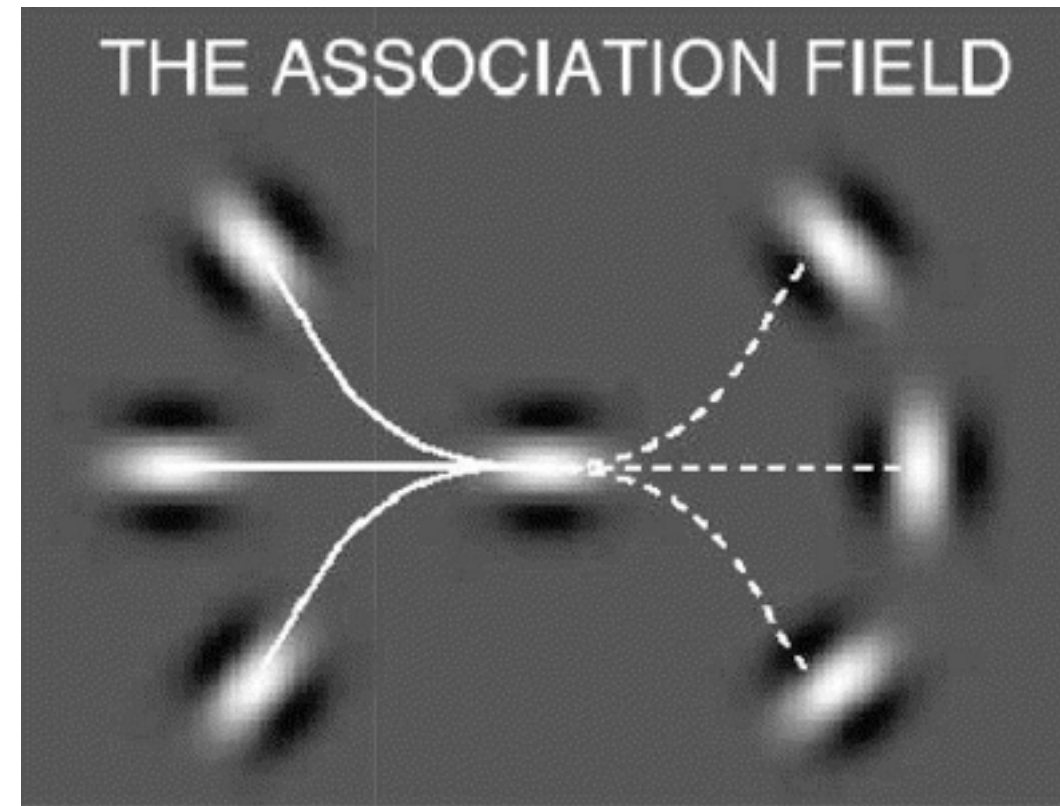
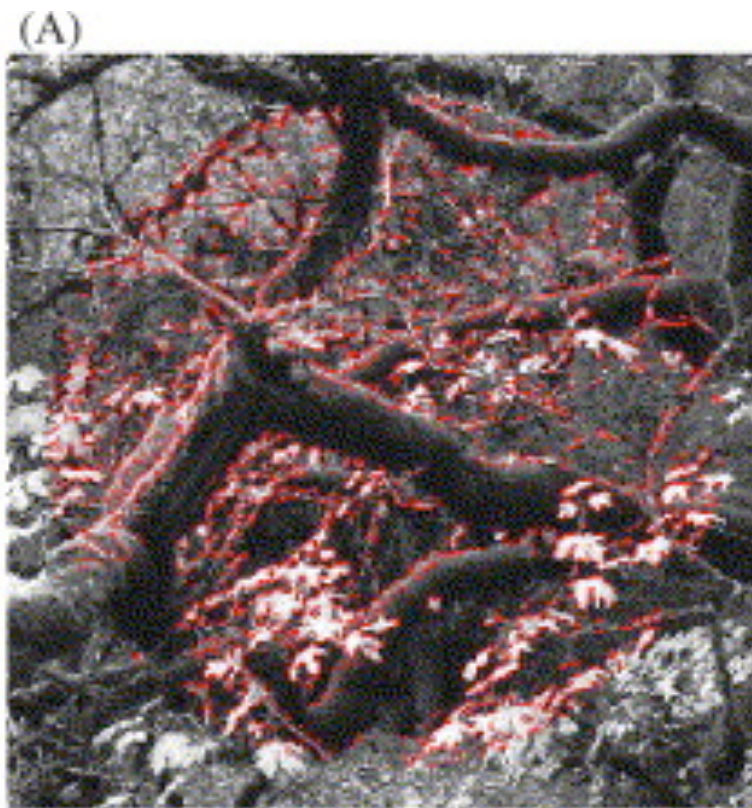


Fig. 2. Co-occurrence statistics of contour elements in natural images. **a.** Definition of parameters describing the geometrical and contrast relationship between a pair of contour elements. **b.** Plot of the likelihood ratio for a given relationship between pairs of contour elements. **c.** Ratio of the prior probabilities that pair of contour elements belong to different versus the same physical source, as a function of distance between the pair of elements. A likelihood ratio greater than 1.0 means (given equal priors) it is more likely that the elements belong to the same physical contour; a ratio less than 1.0 means it is more likely that the elements belong to different physical contours. [For each distance, direction and polarity, the orientation difference bins (line segments) are drawn in rank order starting from the lowest likelihood; thus, the highest likelihoods are the most visible in the plot.]

Natural image statistics cont'd



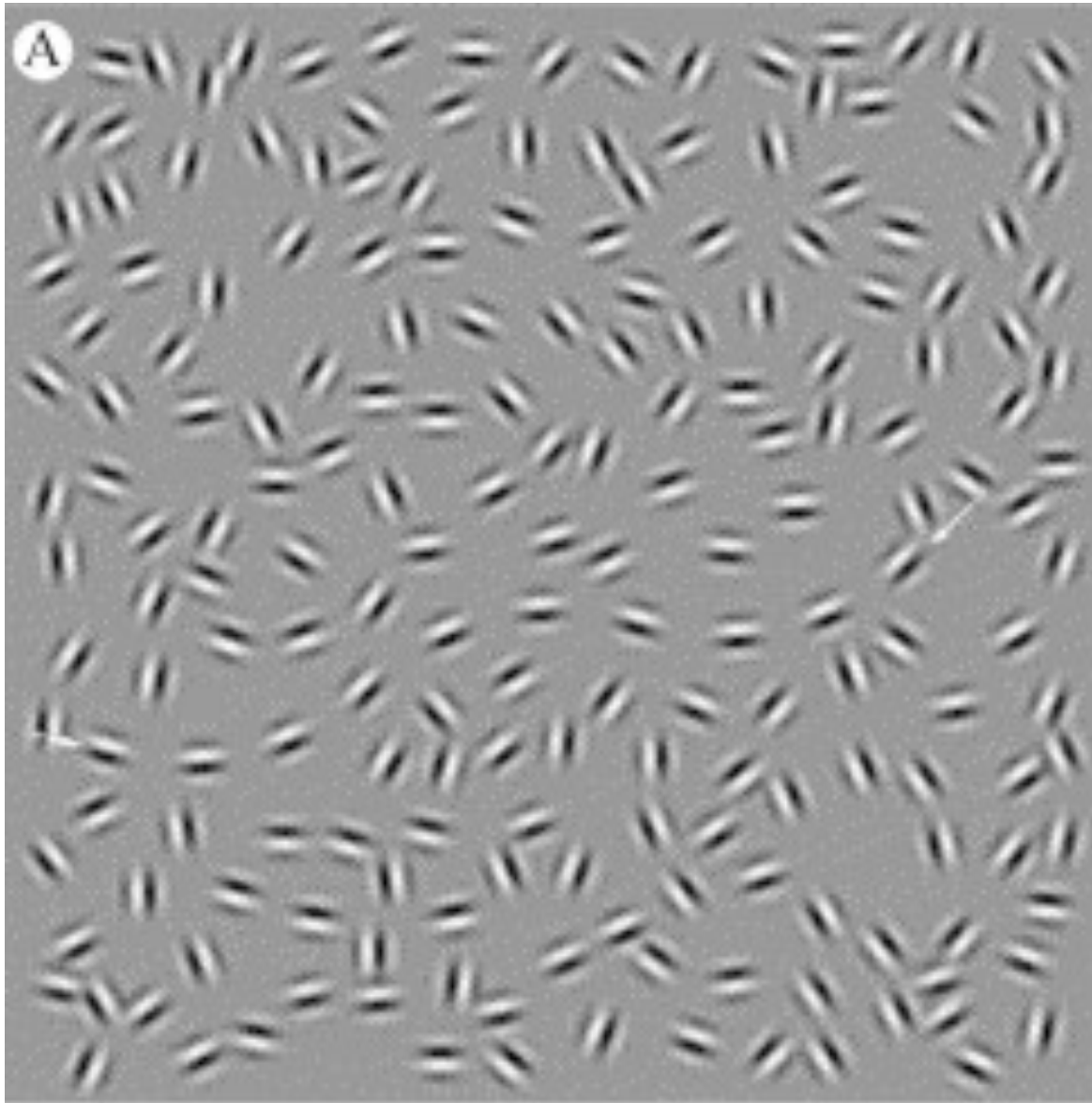
Contour integration only occurs when:-

- Path-Angle change is less than $\pm 60^\circ$
- Spacing between Gabor patches is no greater than 4-6° Gabor wavelength
- The orientation of individual elements is close to that of the contour

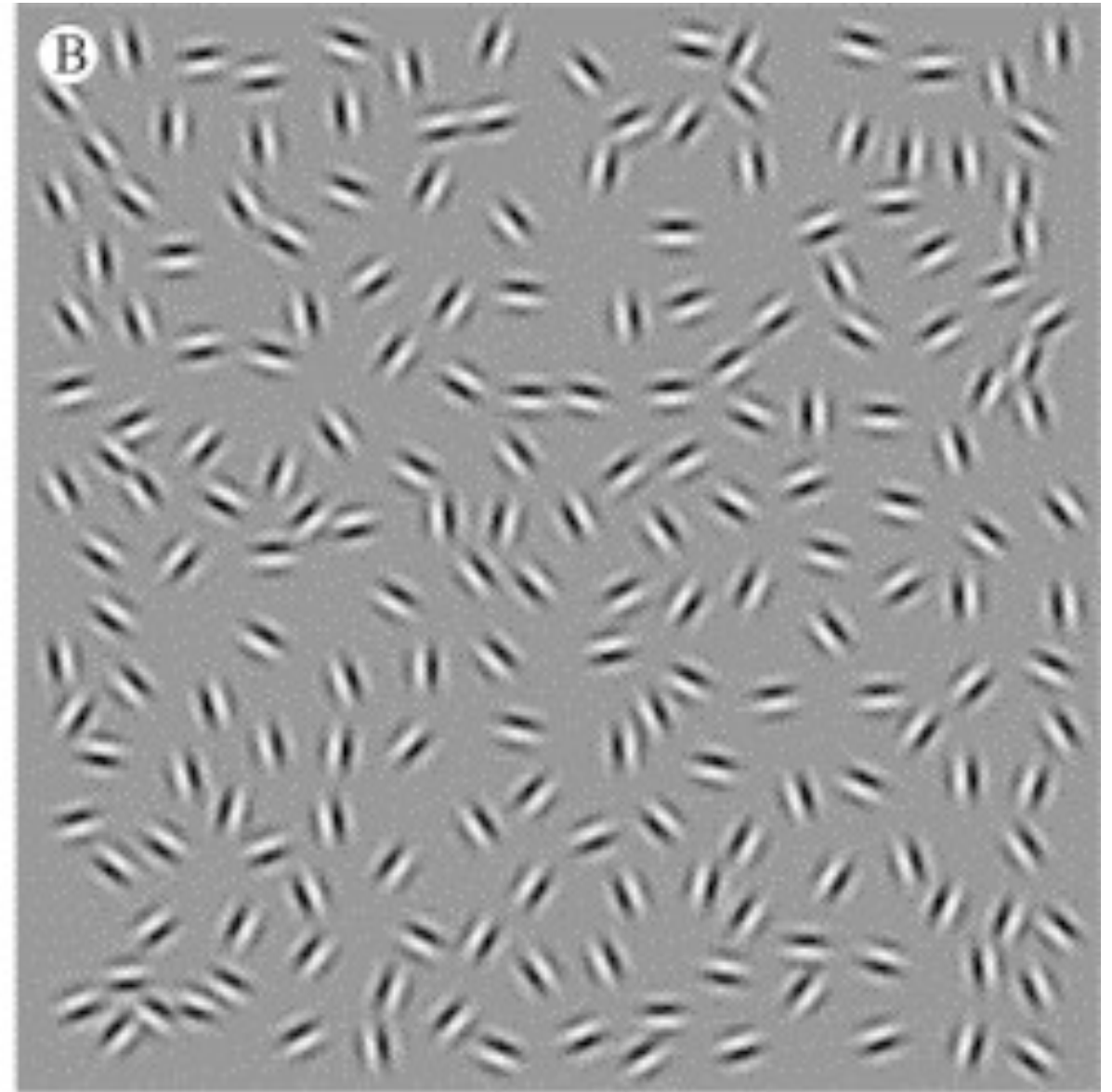
Other Variables:-

The phase of the Gabor patch was found to be irrelevant
Detection improves as the number of elements increases towards 12

Natural image statistics cont'd

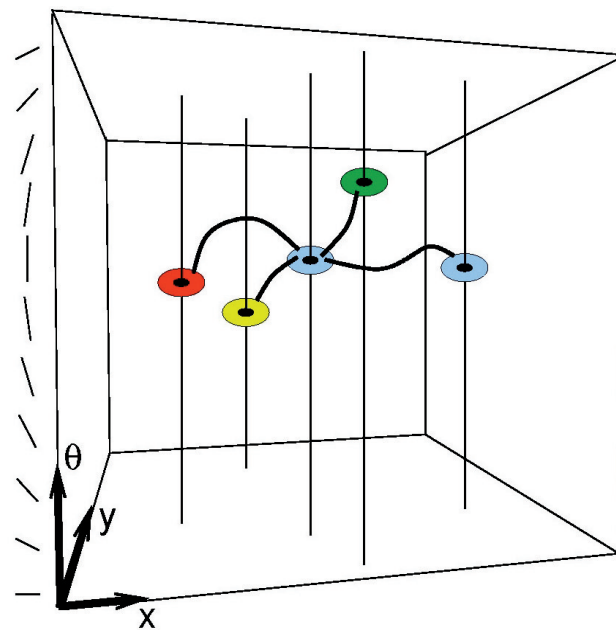


embedded contour

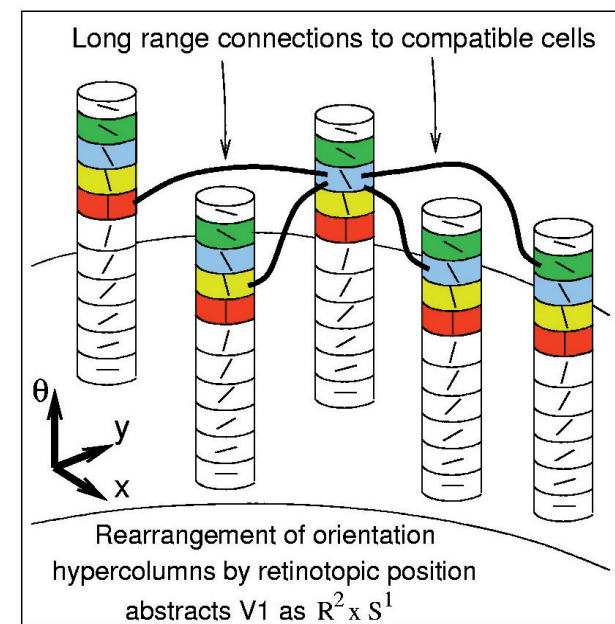


background elements

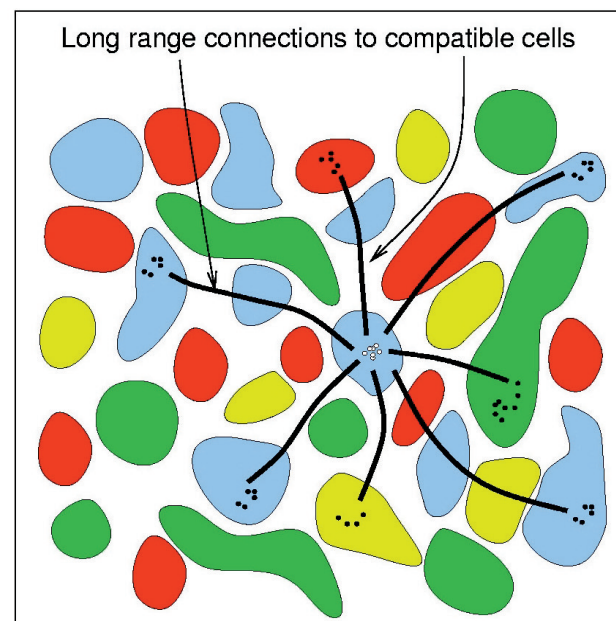
Lateral connections in the primary visual cortex



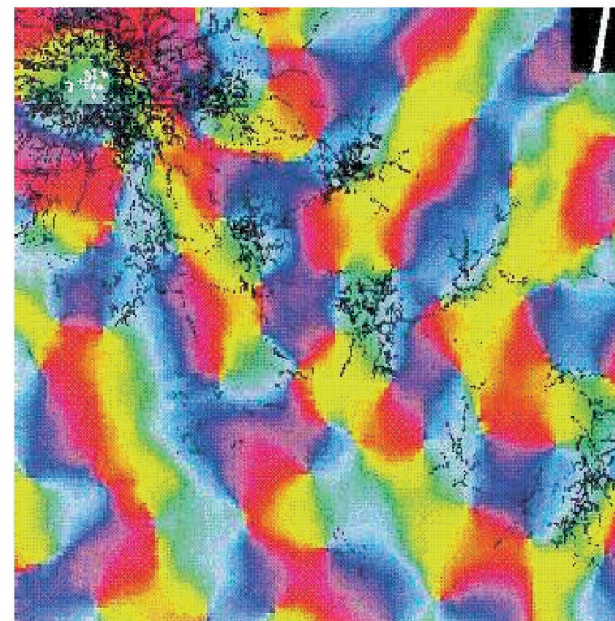
a



b

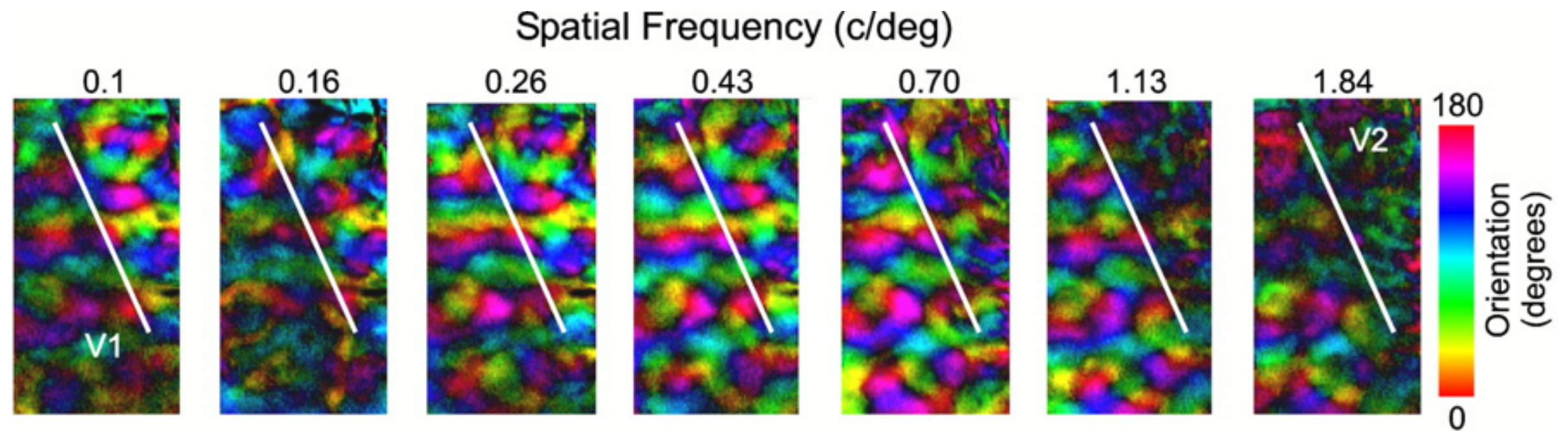


c

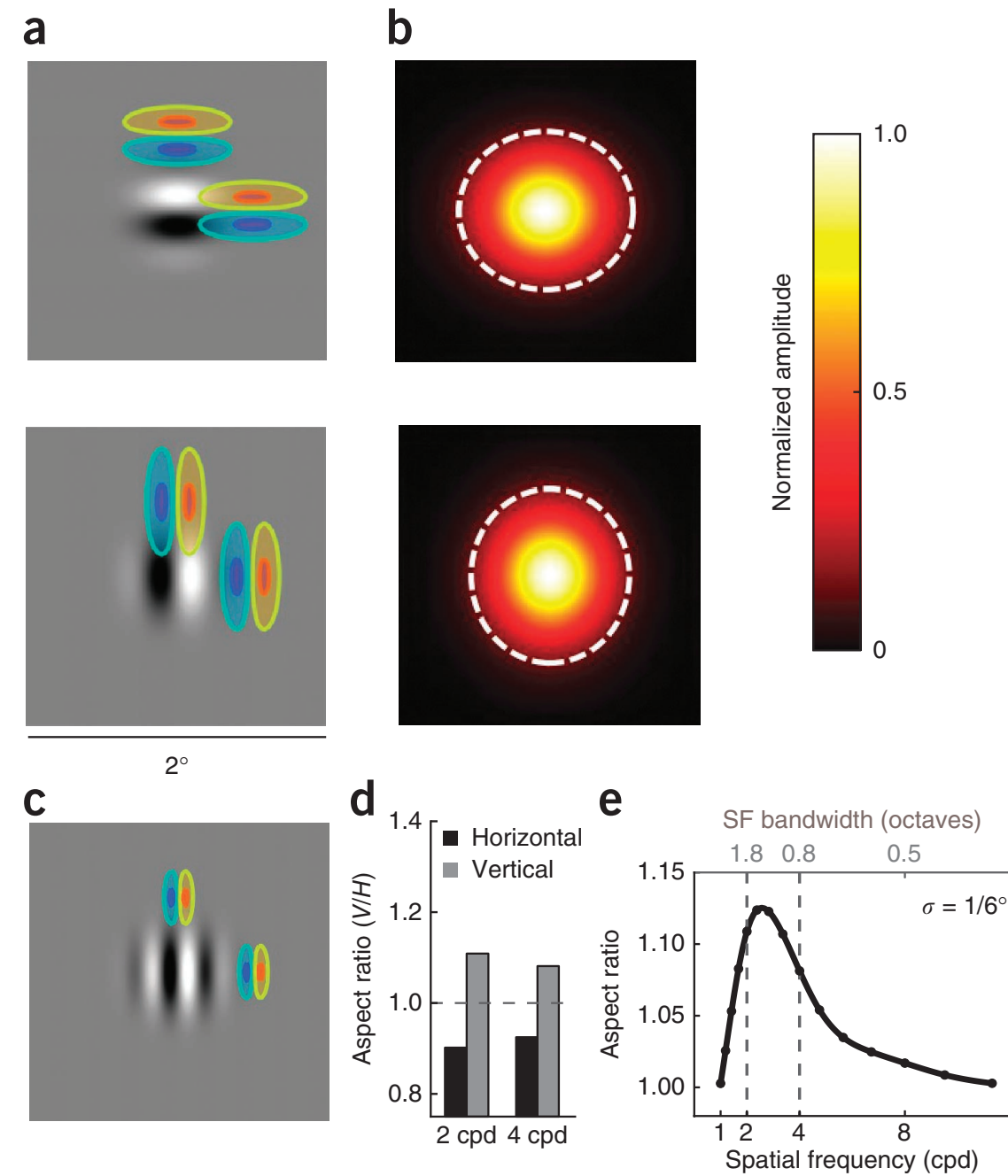
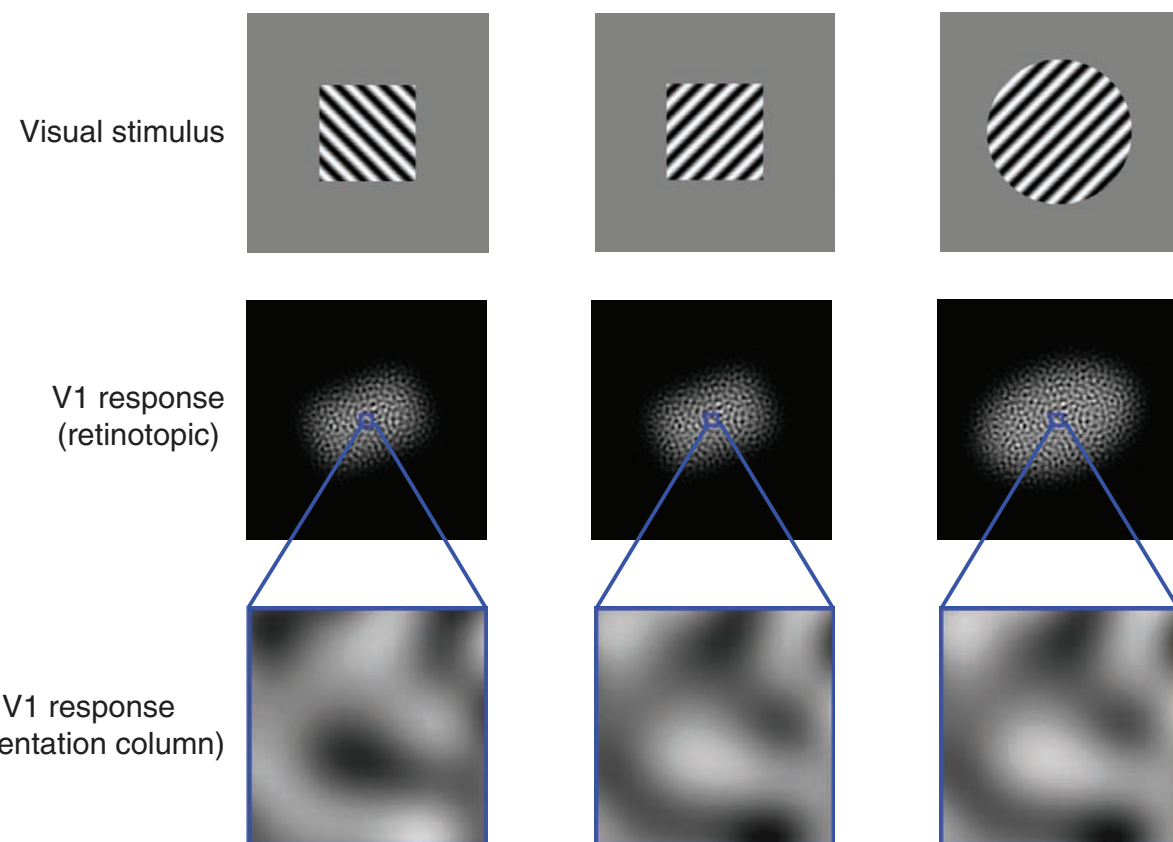


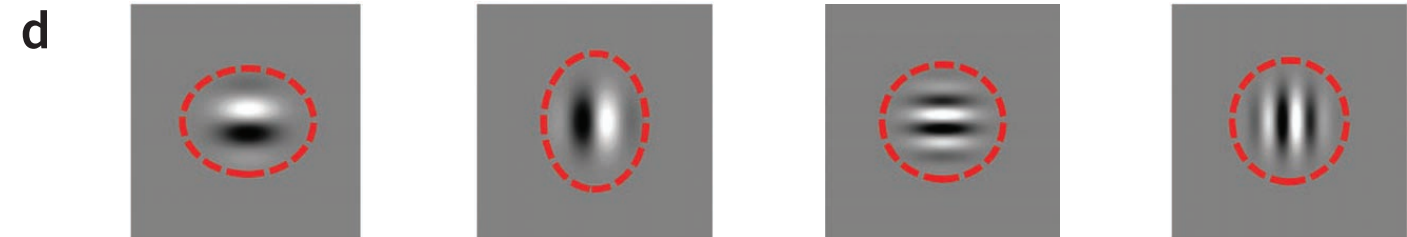
d

Frequency channels



Computing with V1





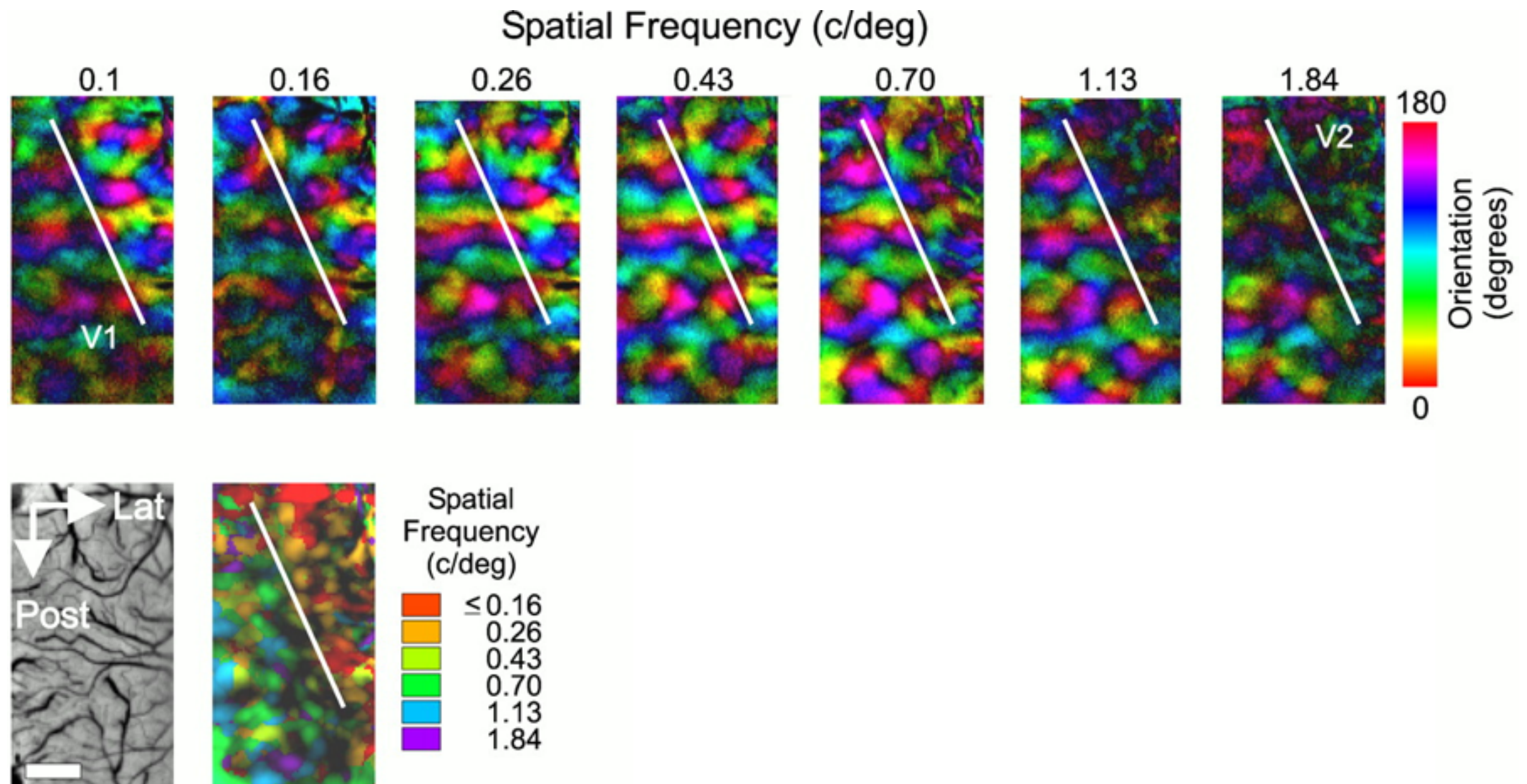
Computational Vision

Primary visual cortex

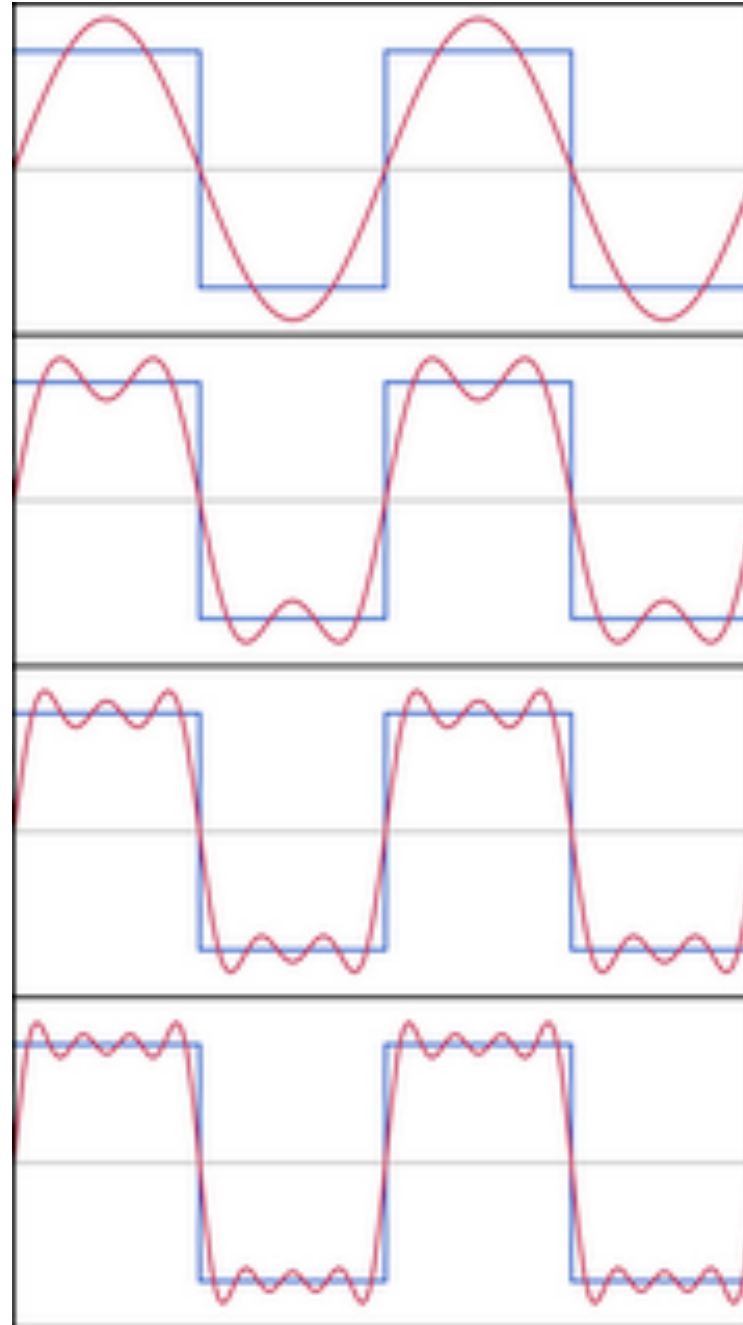
- Orientation selectivity
- **Spatial frequency**
- Color opponency
- Normalization



Frequency channels



Fourier decompositions



Frequency channels

Low spatial frequency



Medium spatial frequency



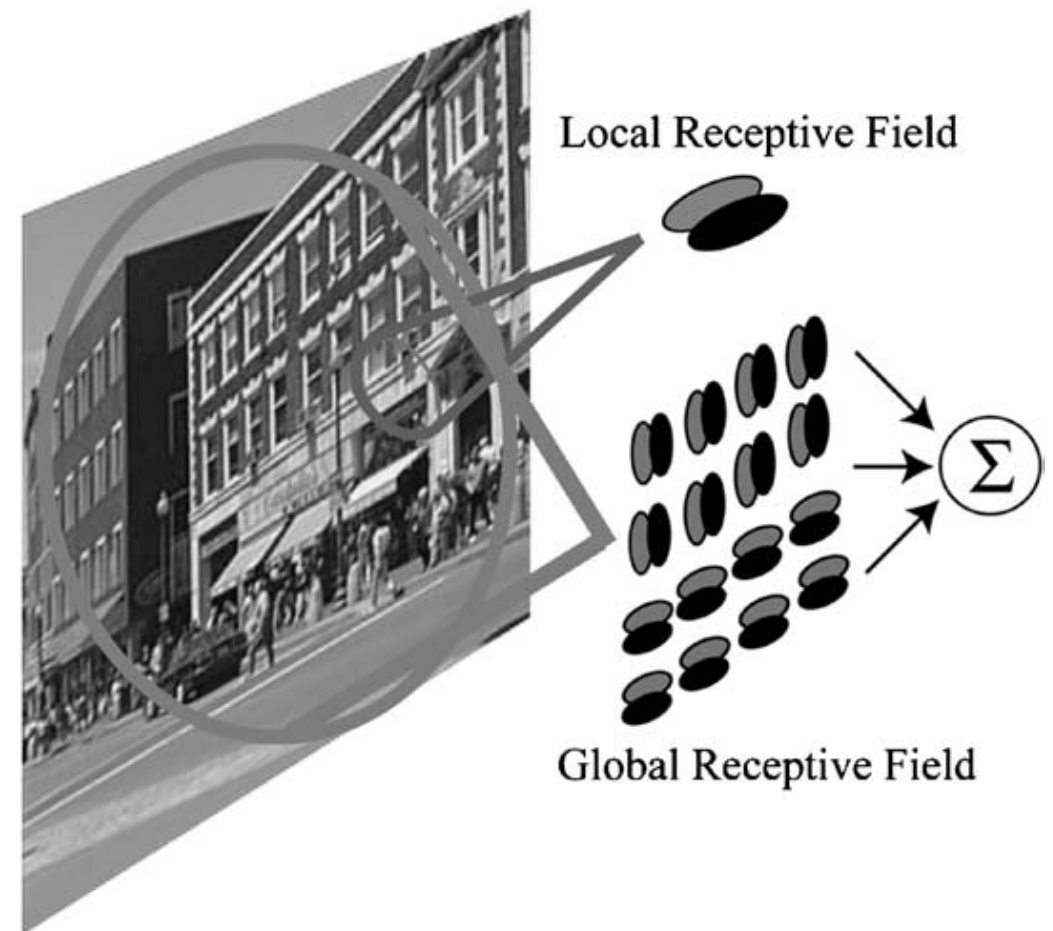
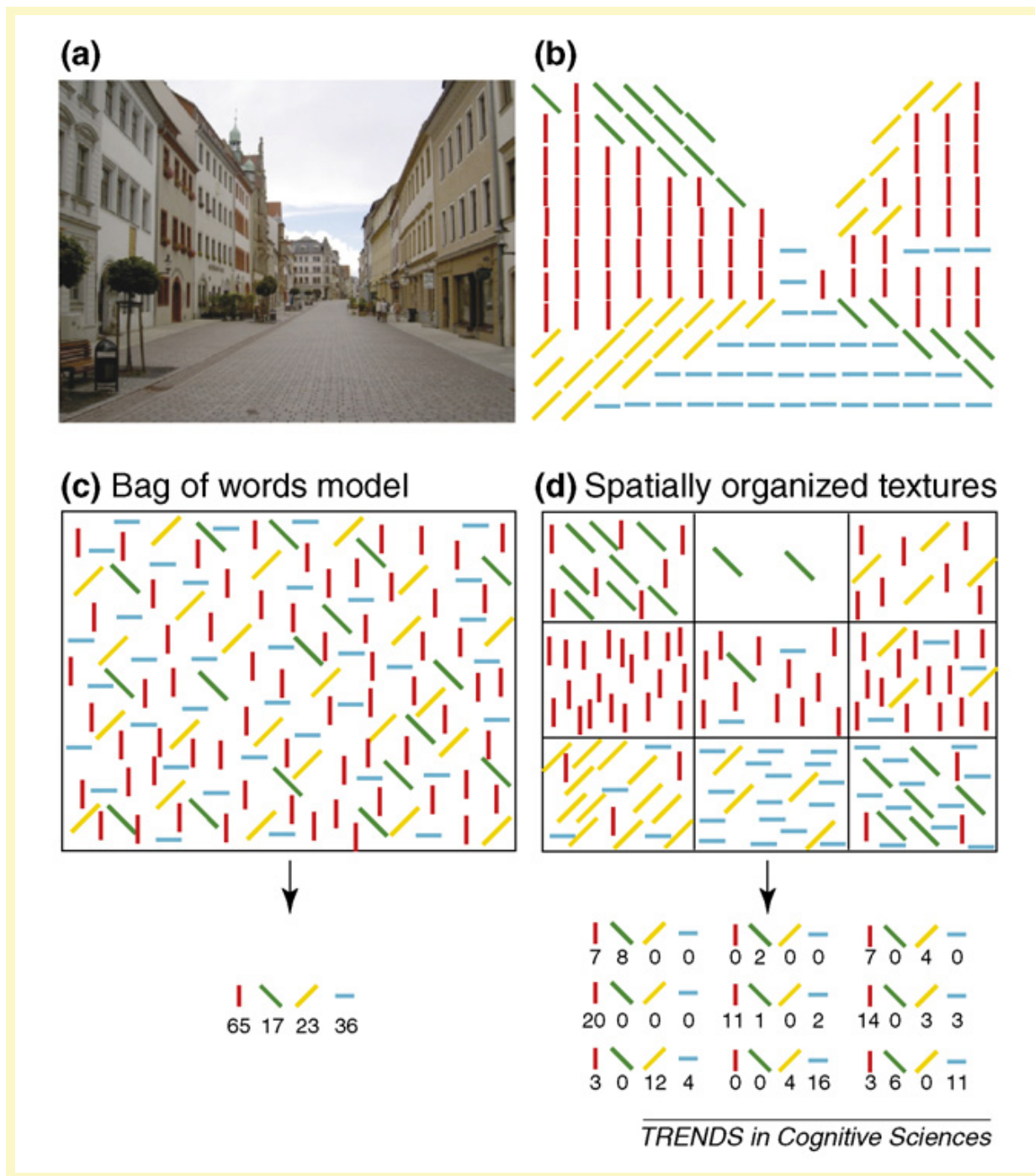
High spatial frequency



Spatial frequency channels

Computing with V1

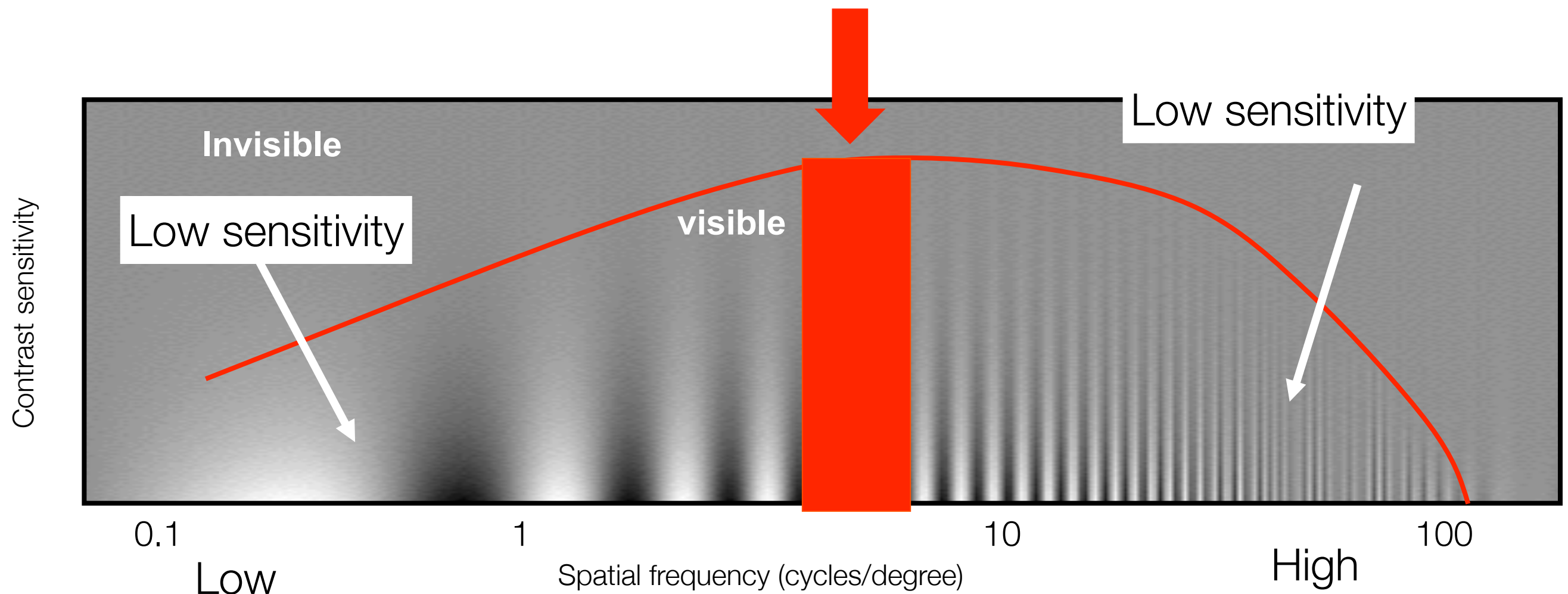
Gist descriptor

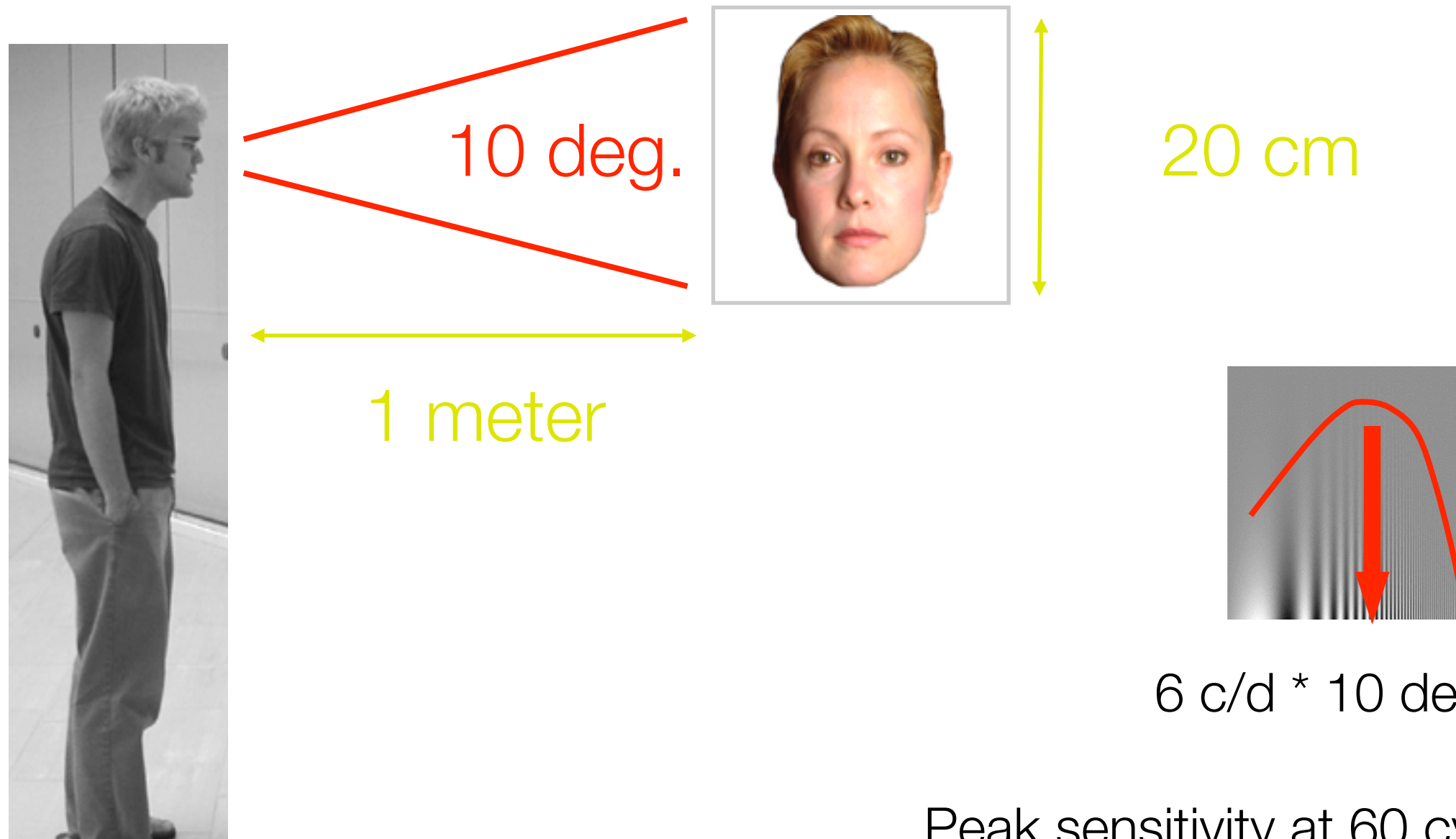


Contrast sensitivity function

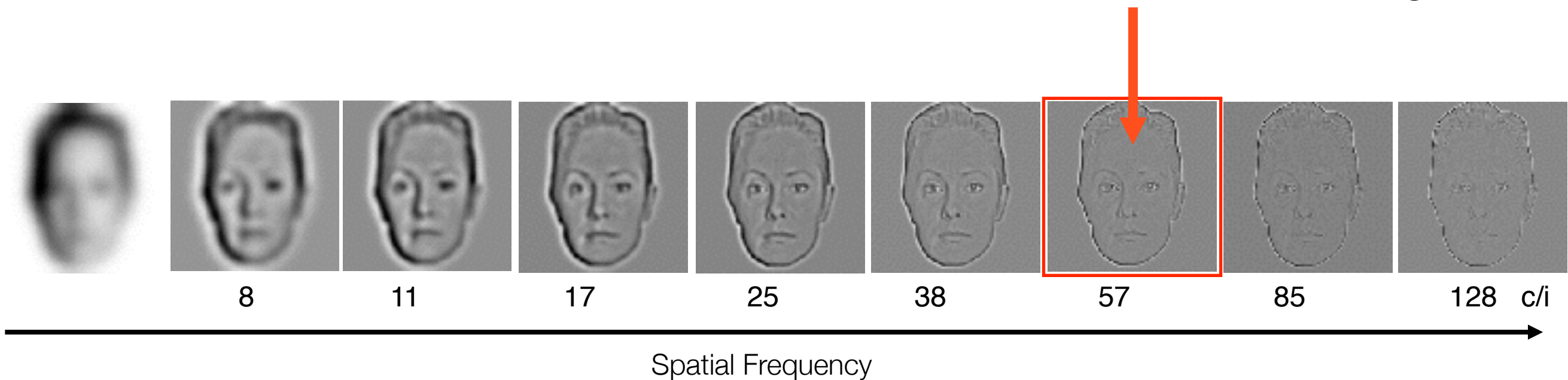
Blackmore & Campbell (1969)

Maximum sensitivity
~ 6 cycles / degree of visual angle





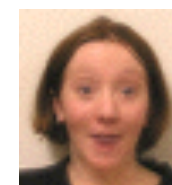
Peak sensitivity at 60 cycles/image



Hybrid Images

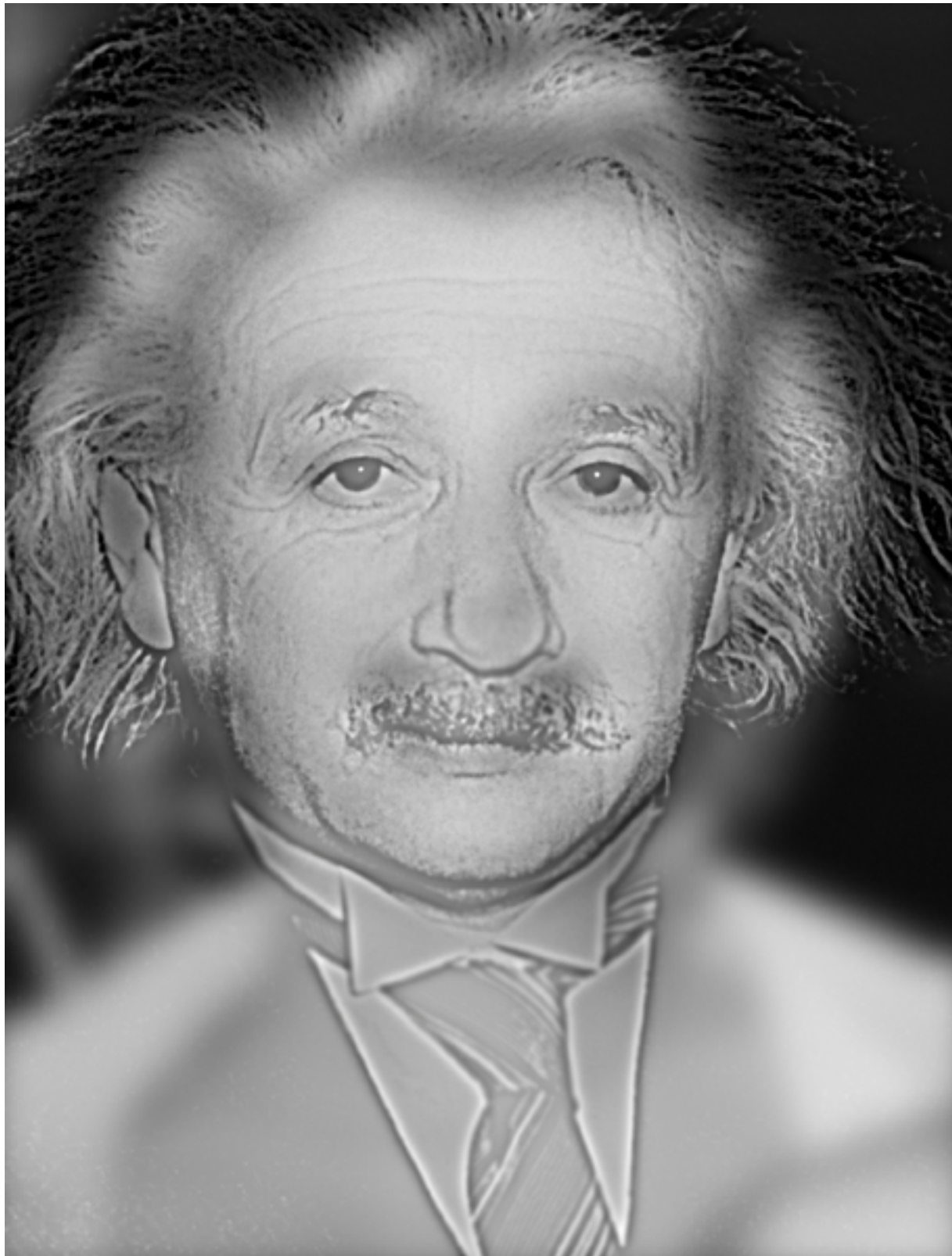


Hybrid Images



Aude Oliva (MIT)

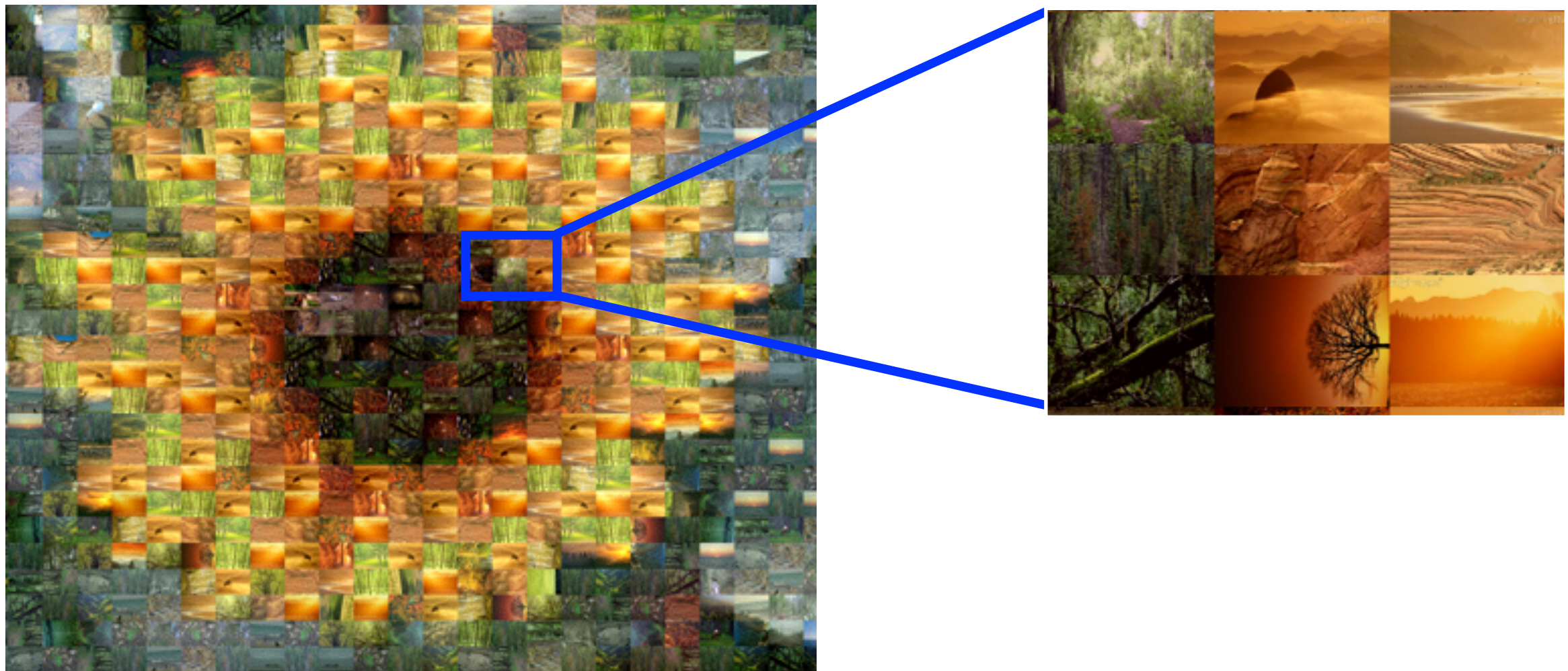
Hybrid Images



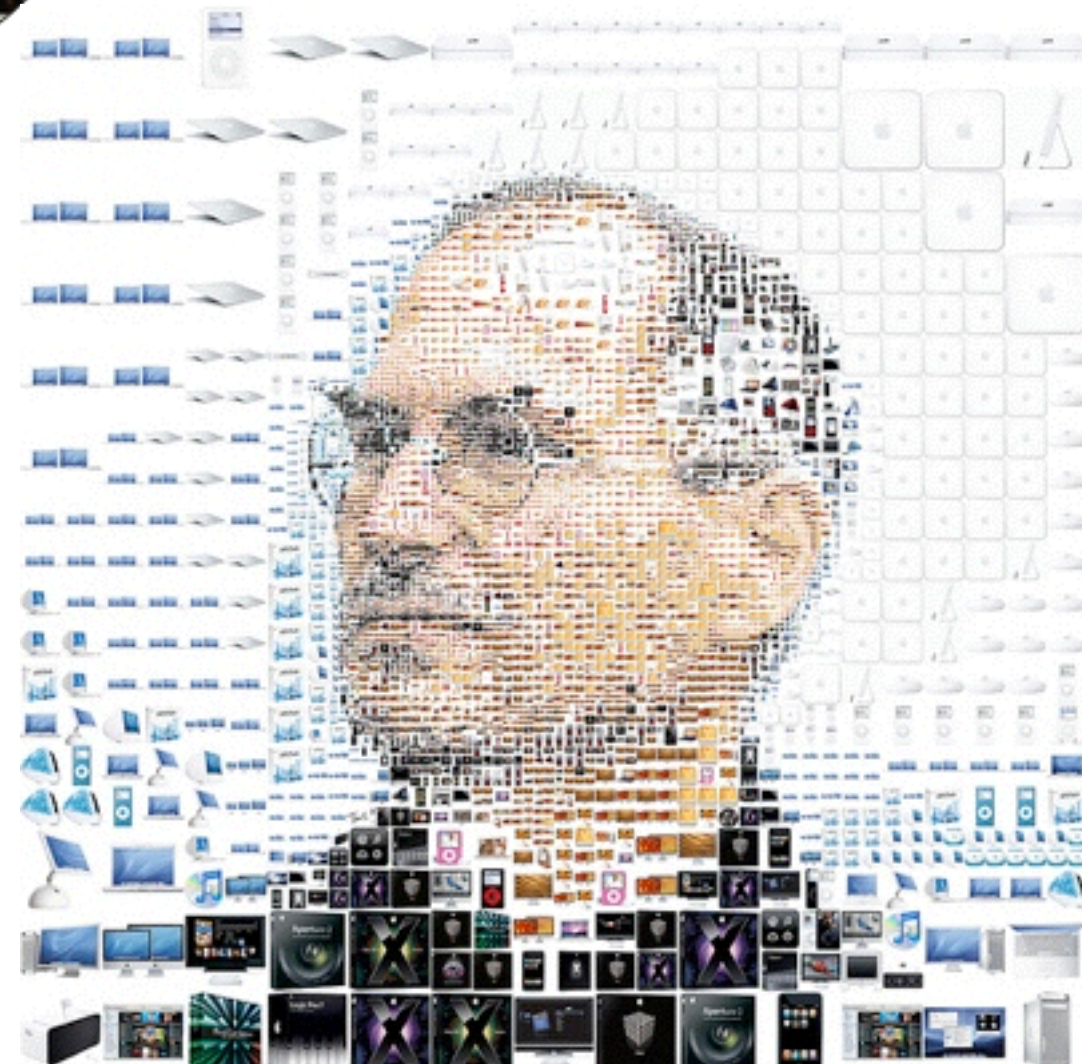
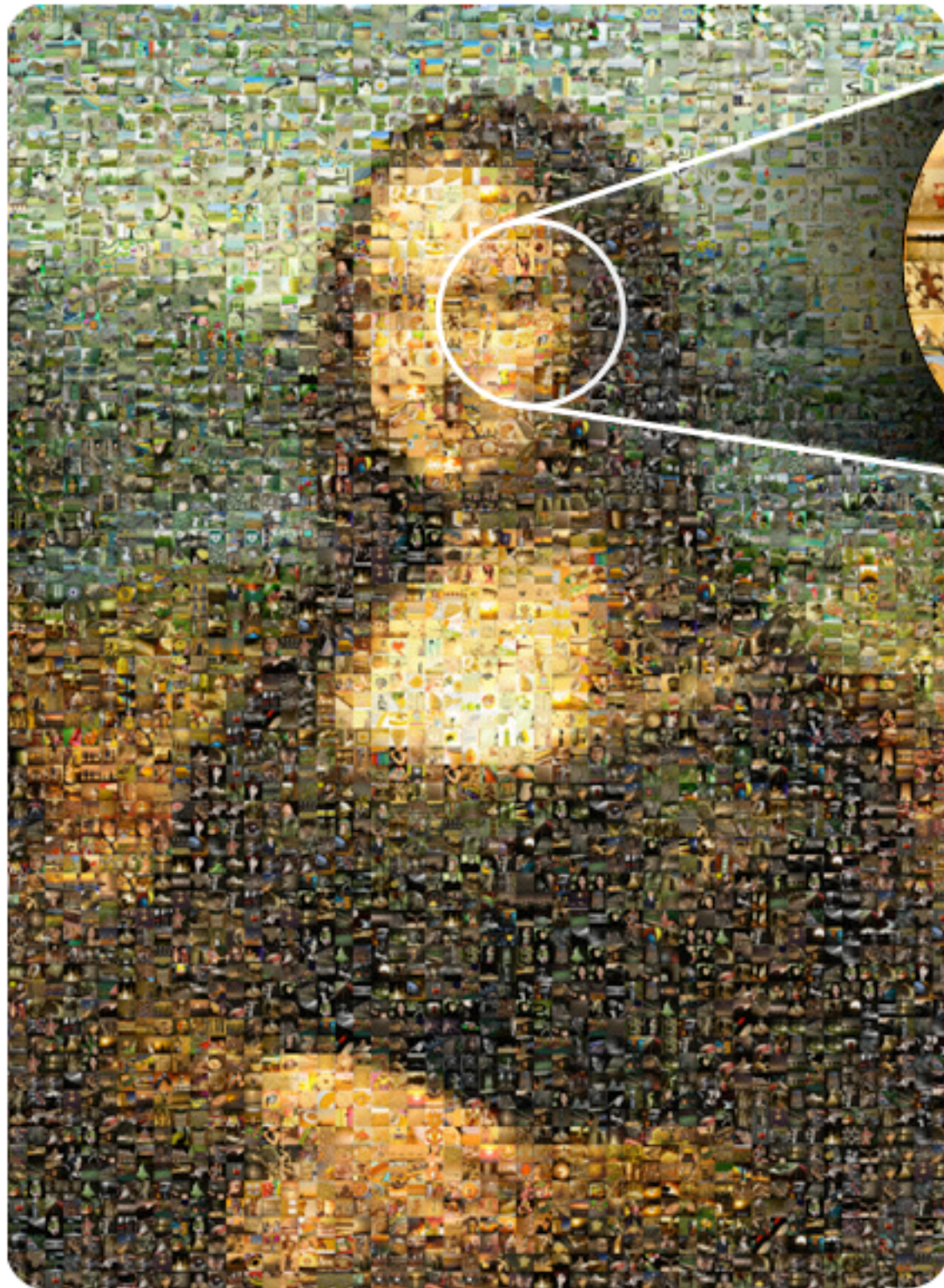
Aude Oliva (MIT)



On the perception of spatial frequencies



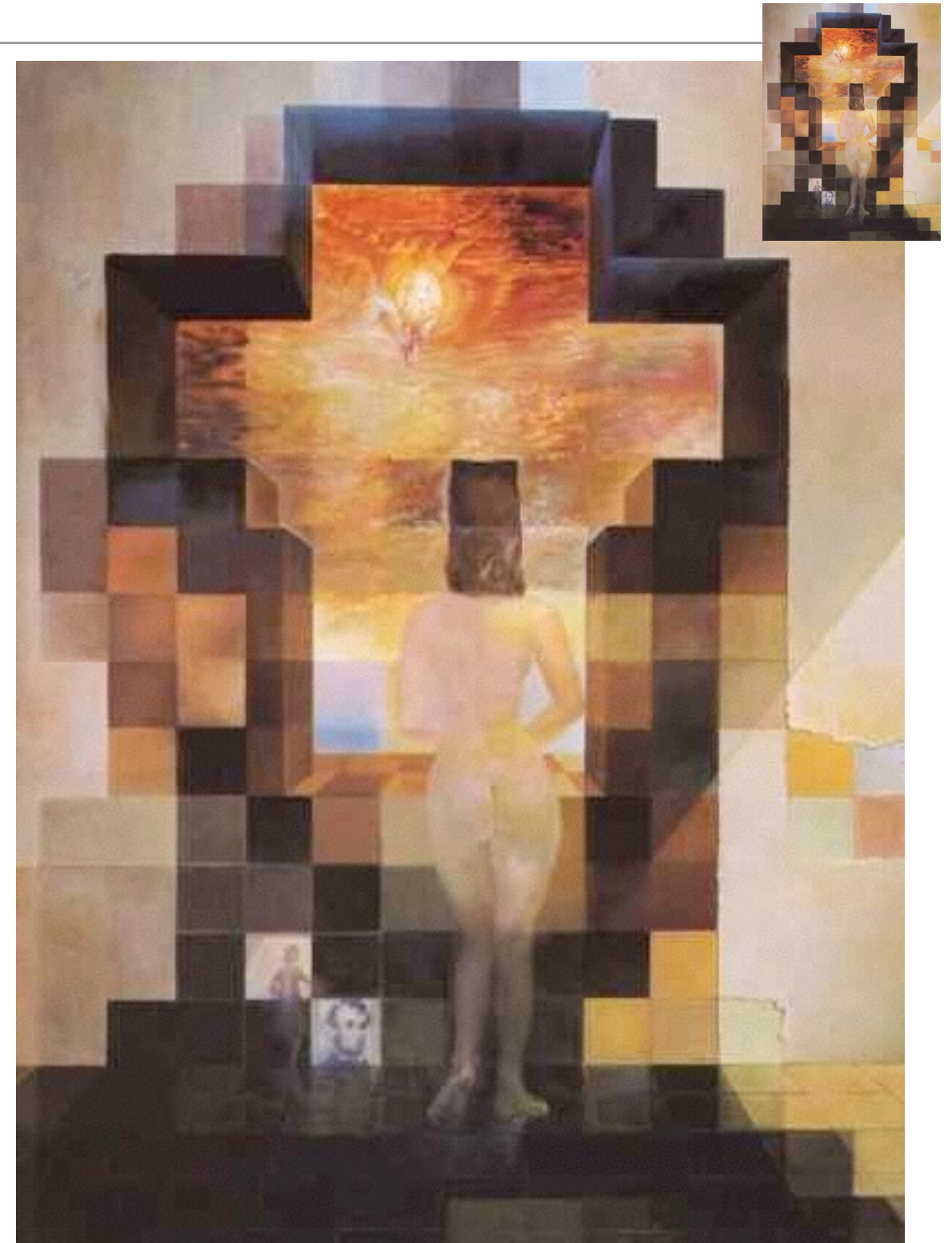
On the perception of spatial frequencies





Dali's *Slave Market with the Disappearing Bust of Voltaire*

On the perception of spatial frequencies

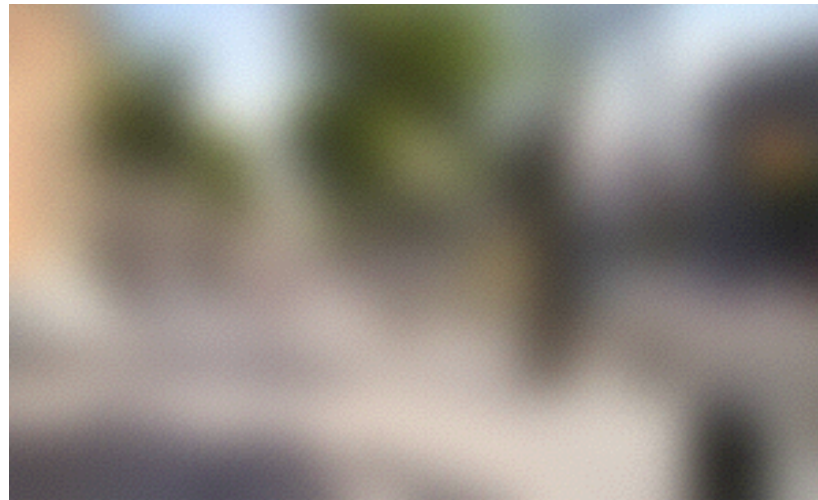




"All Is Vanity", by C. Allan Gilbert 1873-1929.

Frequency channels

Low spatial frequency

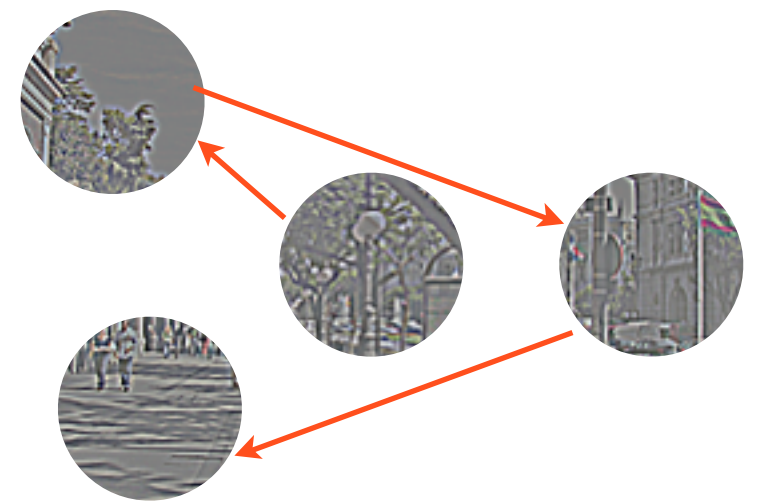


peripheral vision

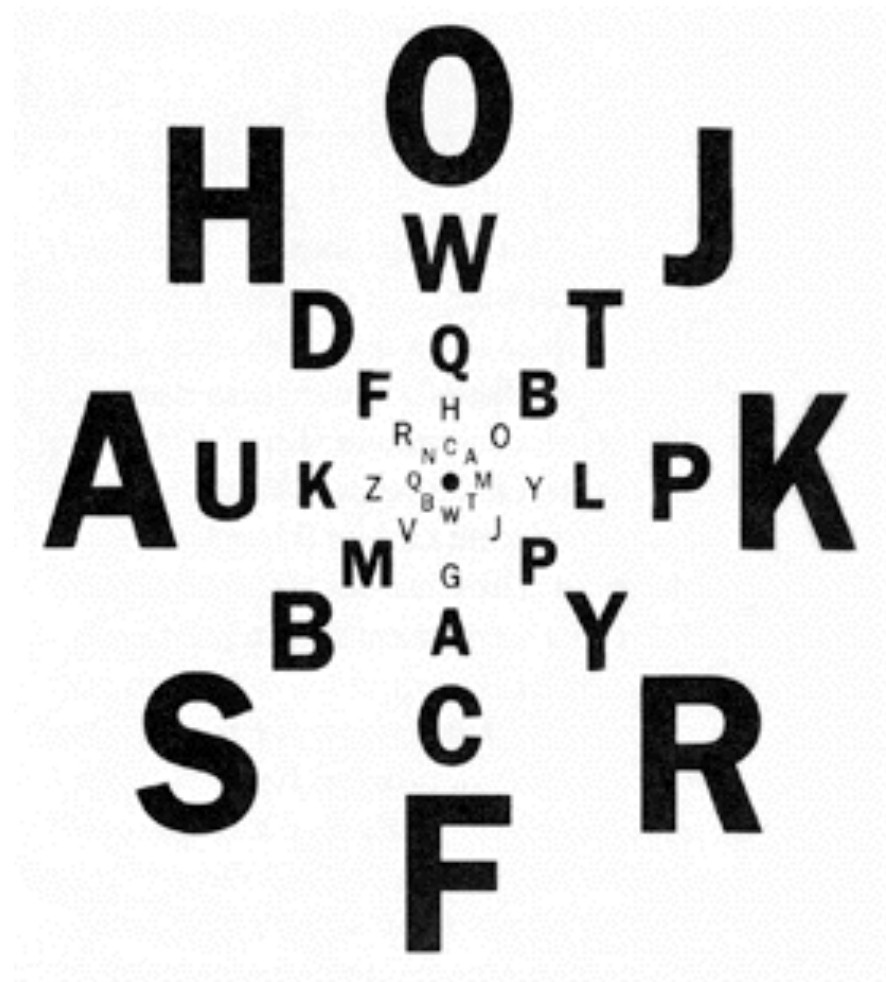


foveal vision

High spatial frequency



Frequency channels



Spatial resolution and acuity



Renoir's Madame
Henriot (1876)

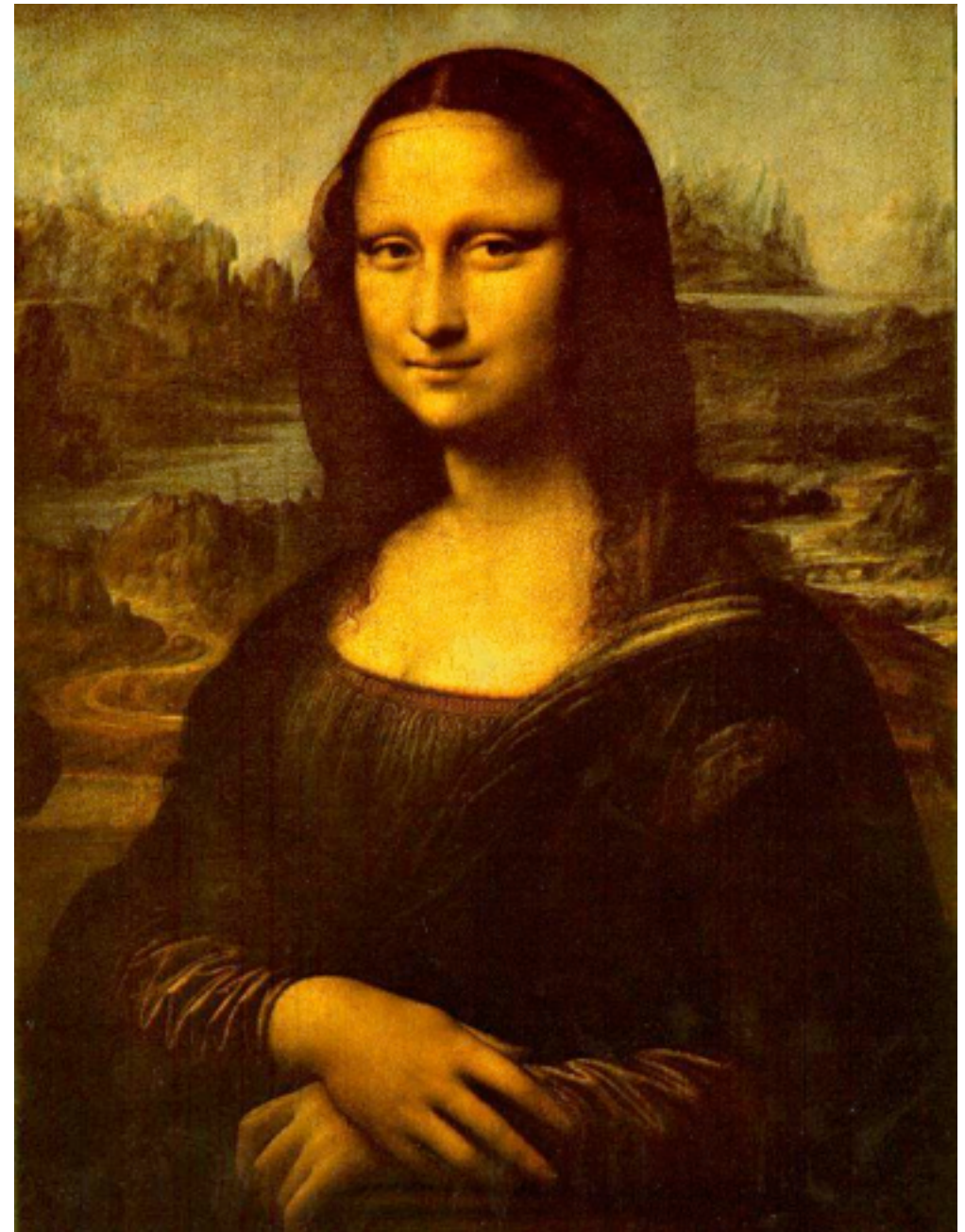
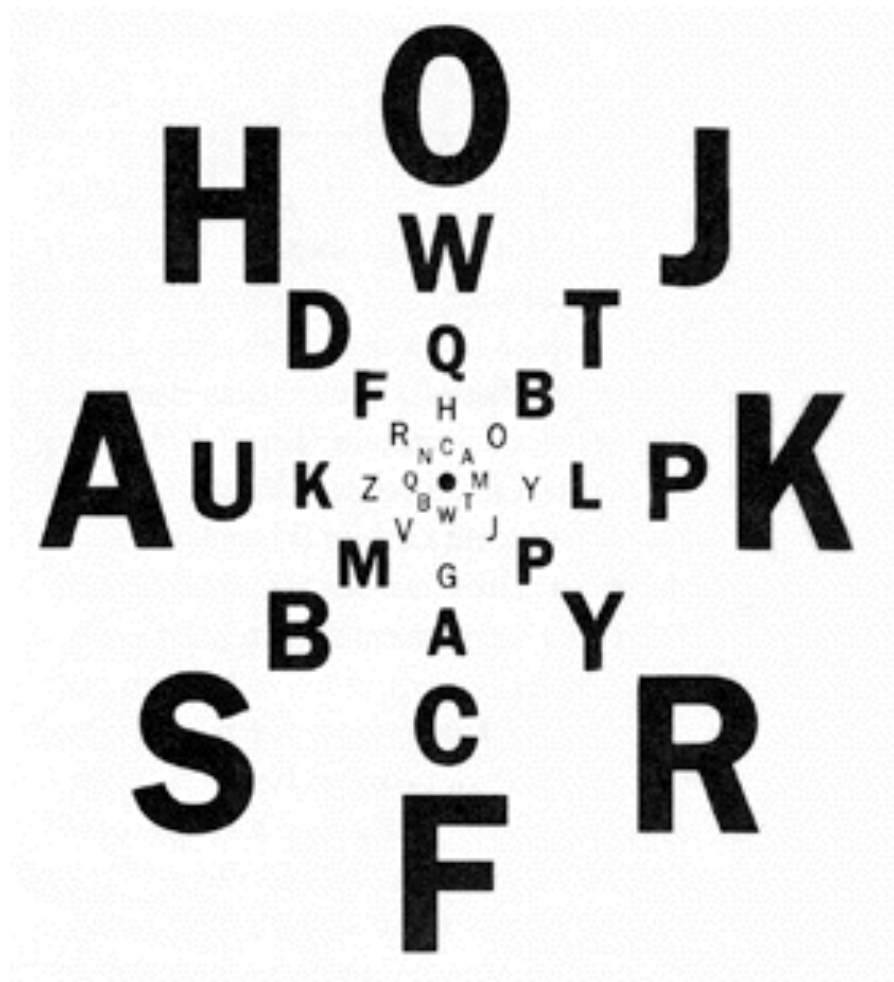


Degas' Woman ironing (1869)



Ingres' Mrs Charles
Badham (1816)

Spatial resolution and acuity



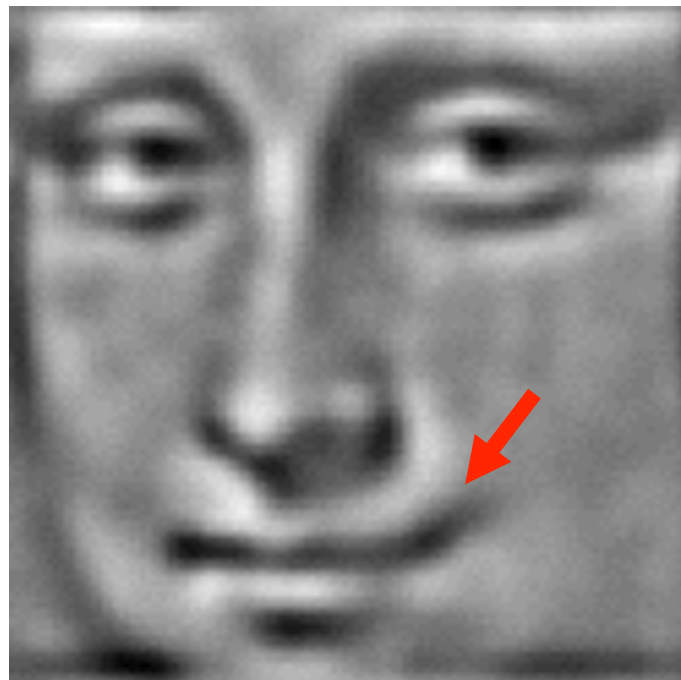
Subtle expression

Leonardo da Vinci's Mona Lisa

Smile



Smile



No smile



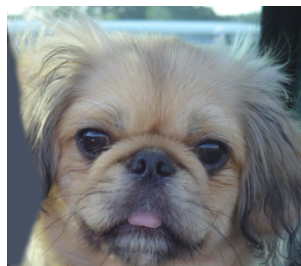
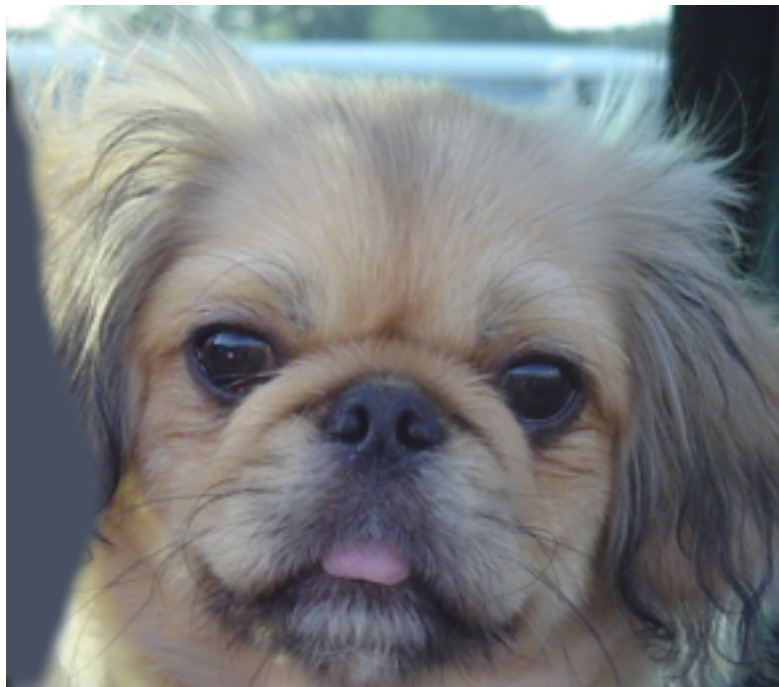
Low

Spatial frequency

High

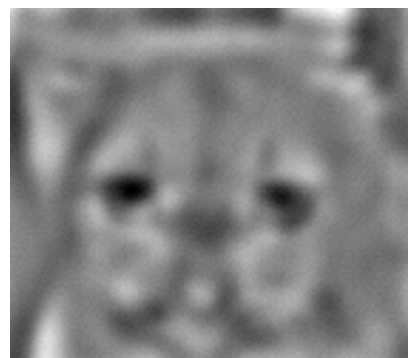
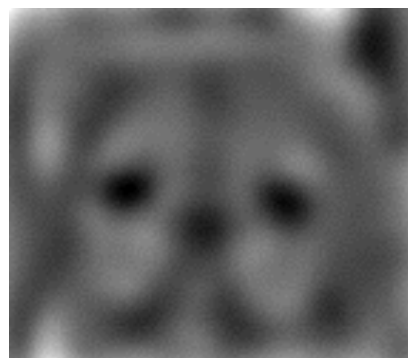
Hybrid Images





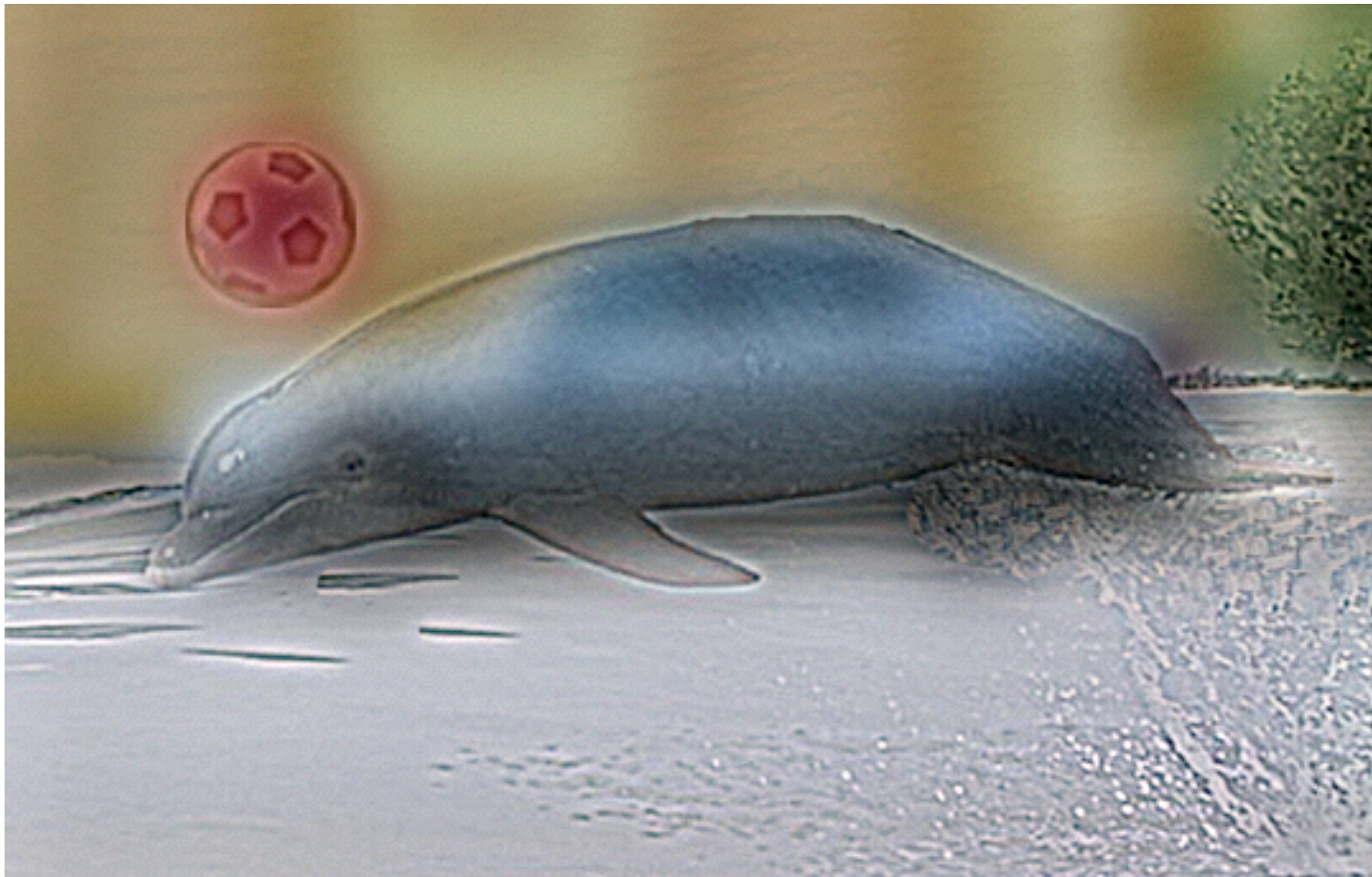
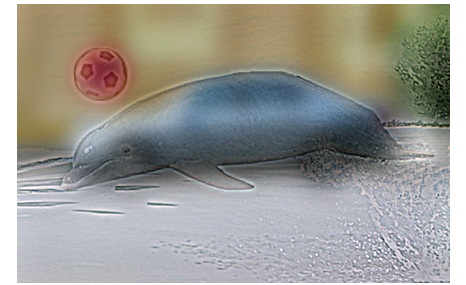
Dog

Cat



matlab run_pyr

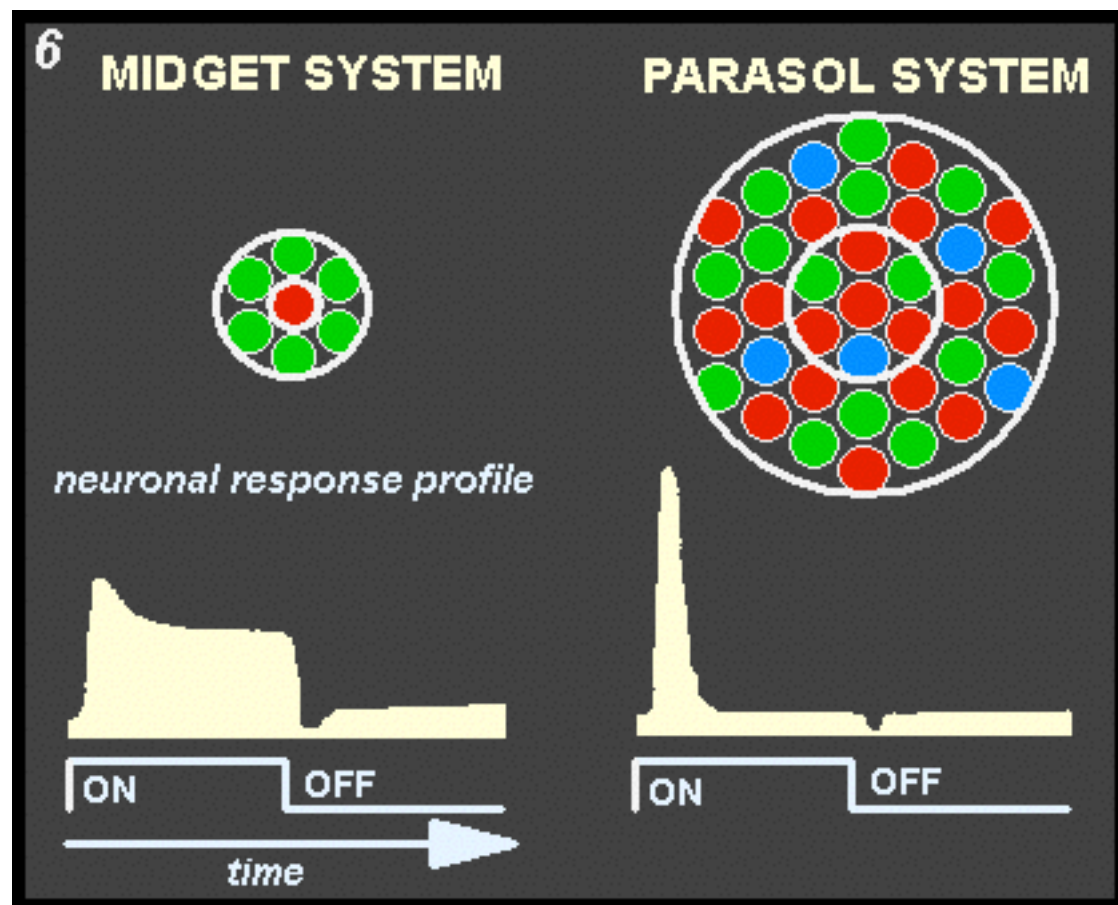
Hybrid Images



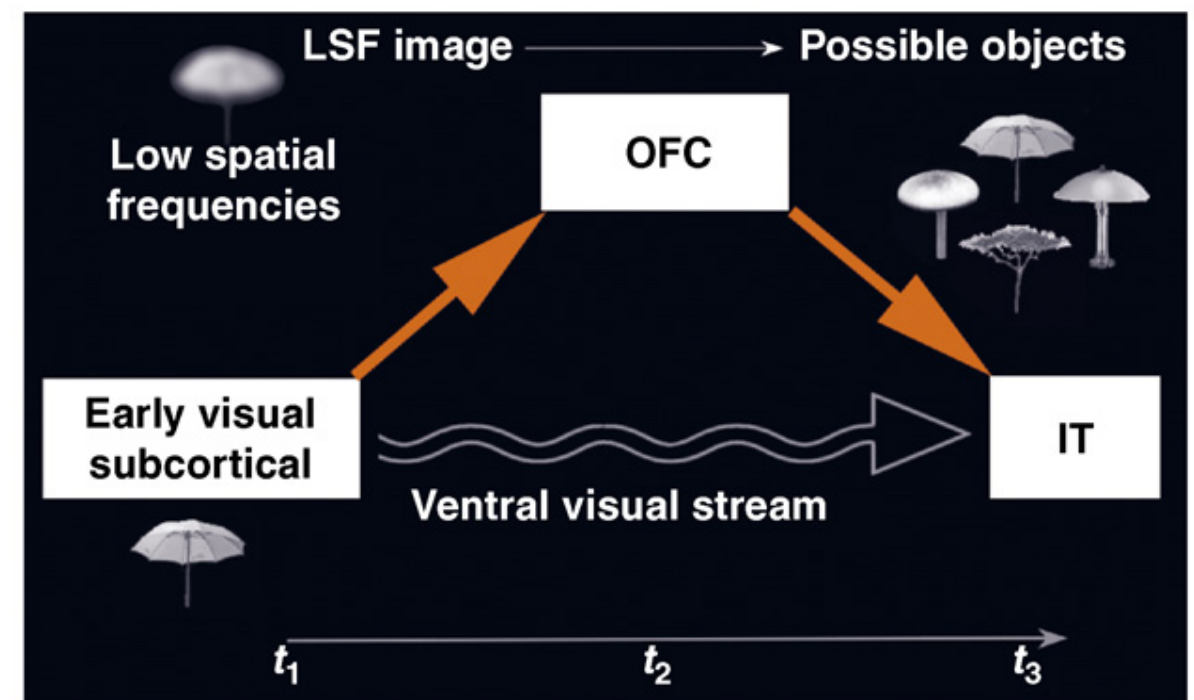
Theories of object recognition

high SF (slow)

low SF (fast)

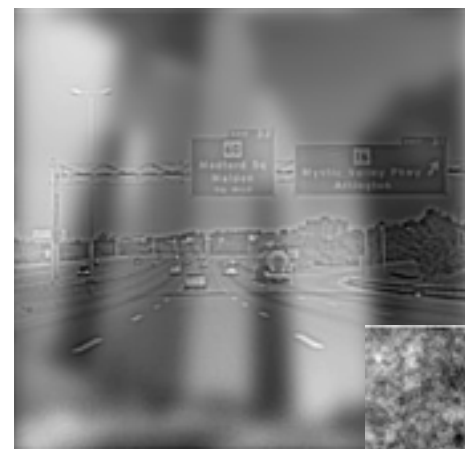


source: Peter Schiller

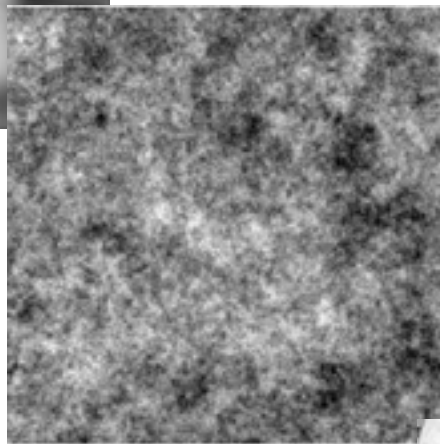


Bar '07

Coarse-to-fine processing



30ms



40ms



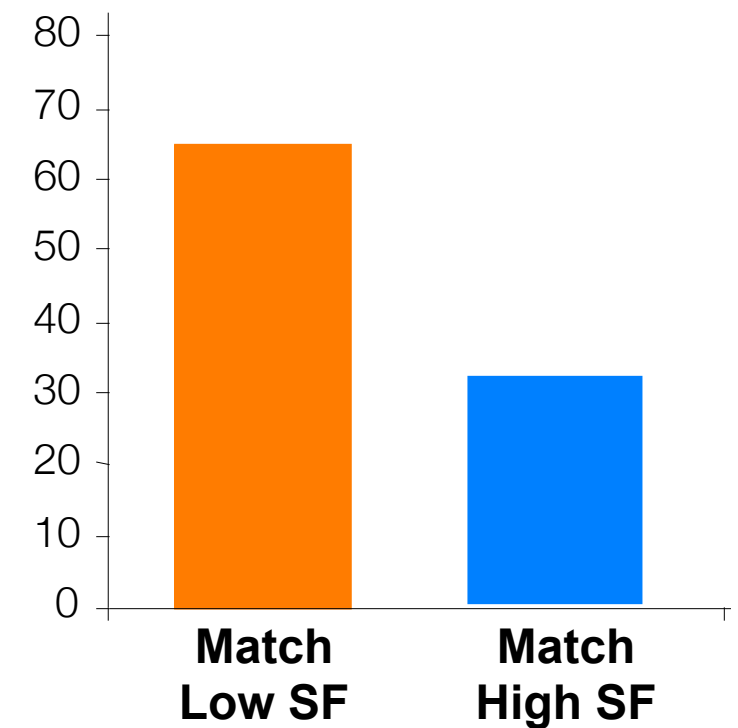
time

Same or different ?

Schyns & Oliva '94

Duration: 30 ms

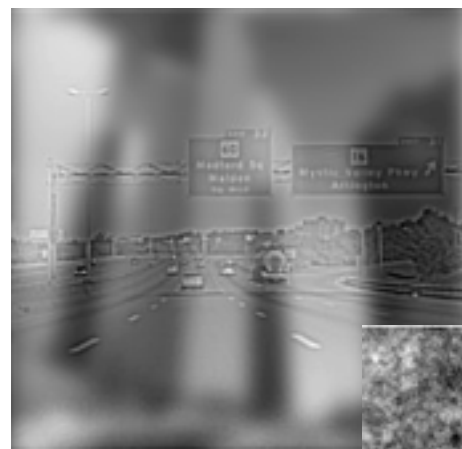
% correct



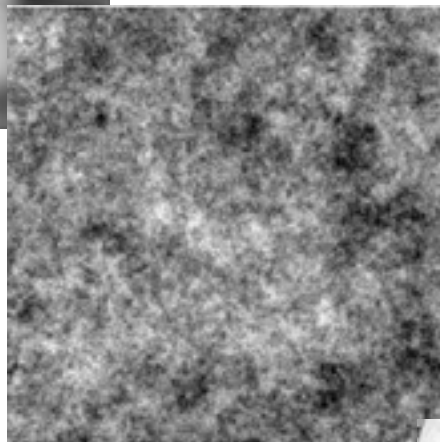
The second image can be:
New image
Match to Low SF (city)
Match to High SF (highway)

Coarse-to-fine processing

Duration: 120 ms



120ms



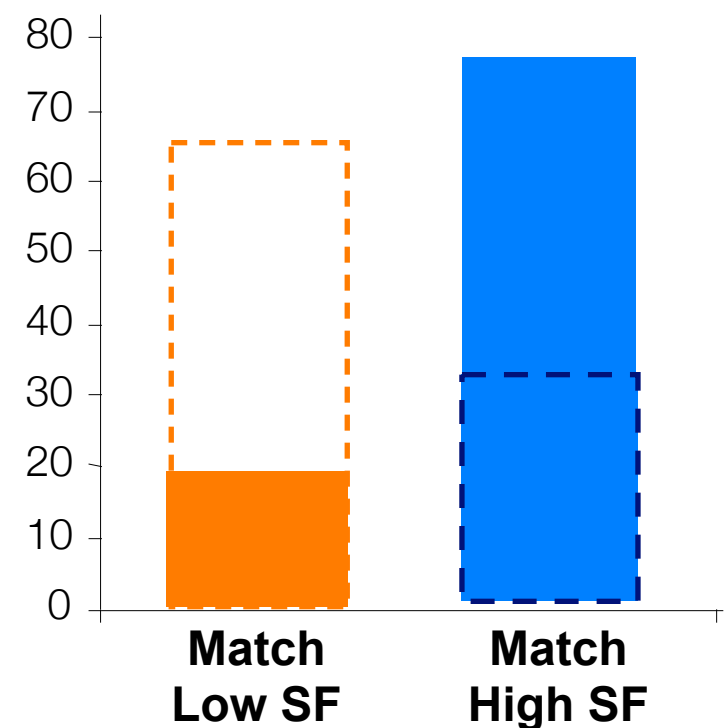
40ms



time

Same or different ?

% correct

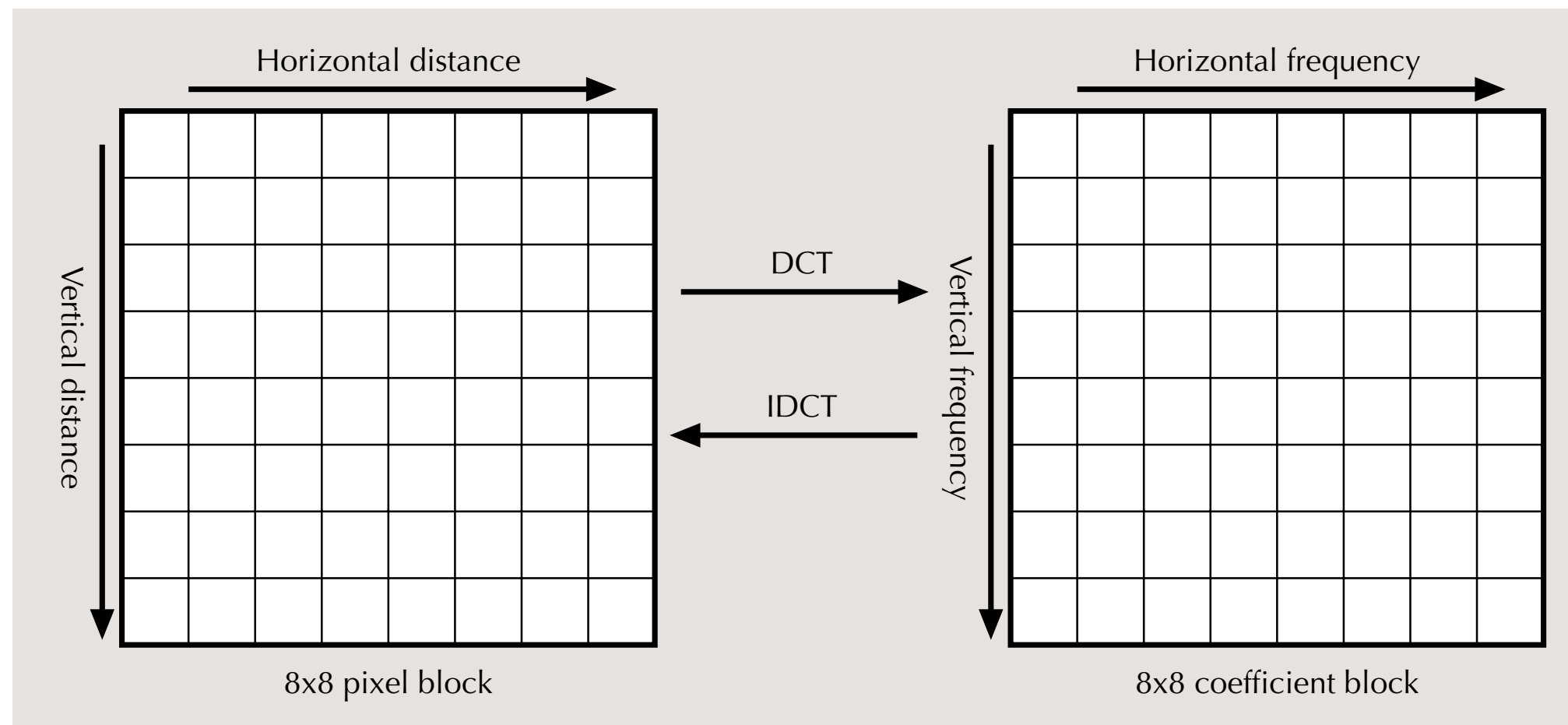
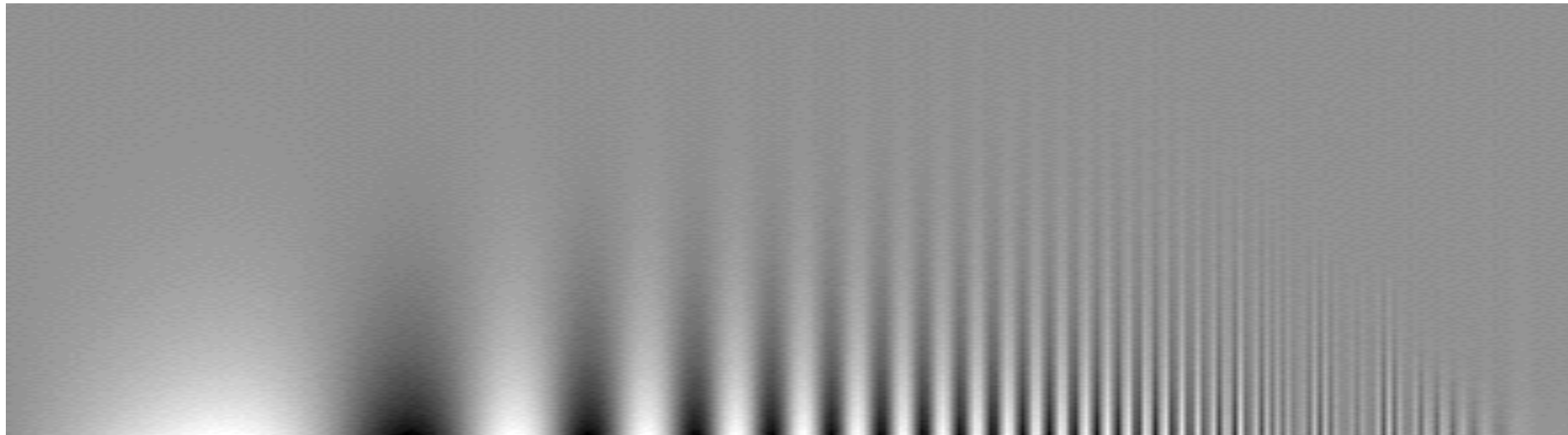


The second image can be:
New image
Match to Low SF (city)
Match to High SF (highway)

Data compression

Based on principles of human vision that we just discussed, how would you use image pyramids/spatial frequency channels for data compression applications?

Contrast sensitivity function

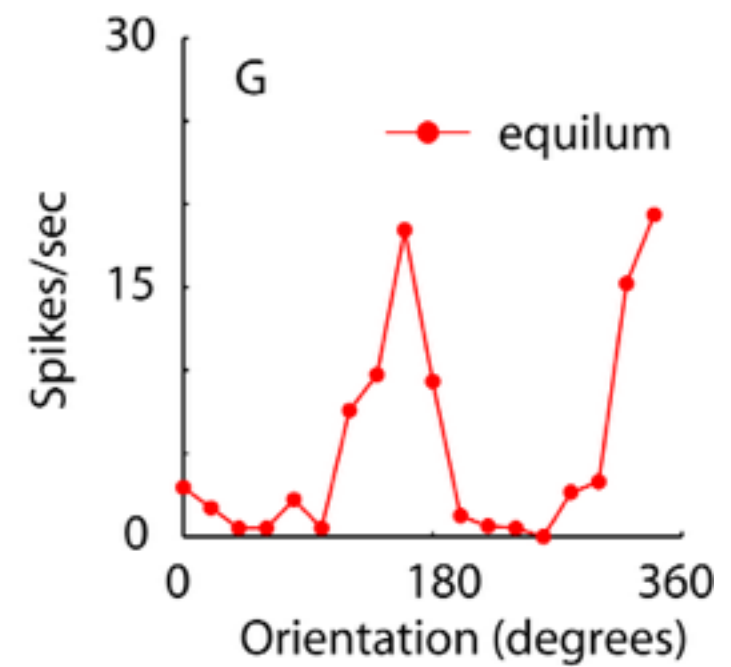
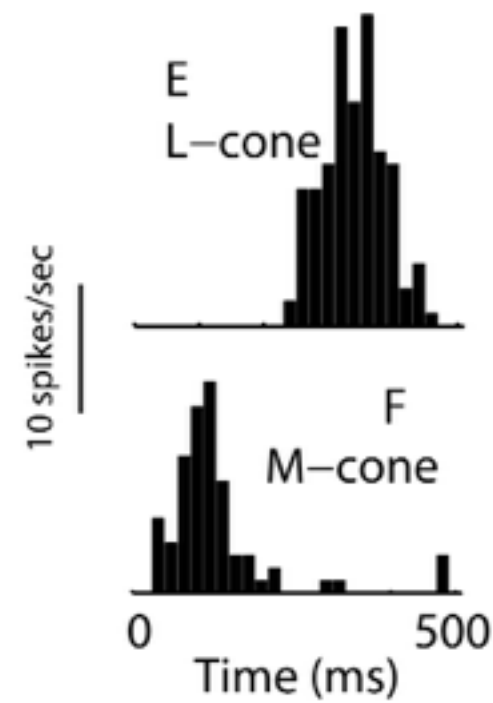
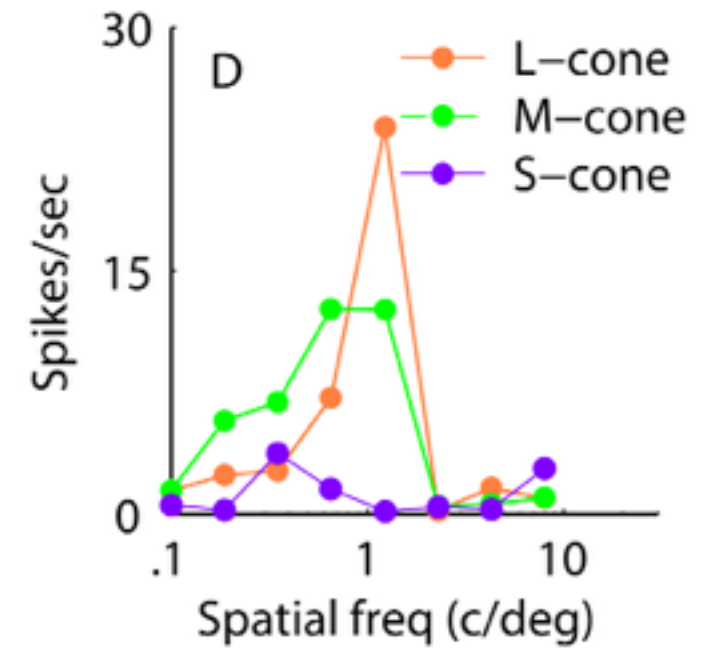
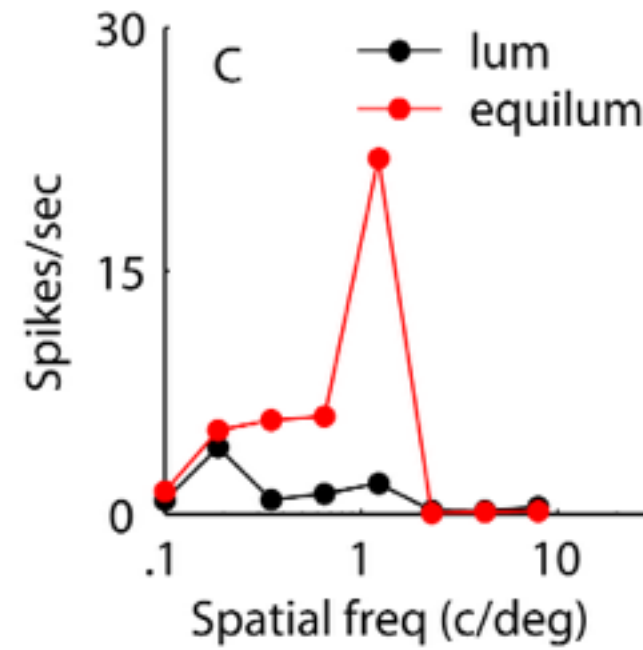
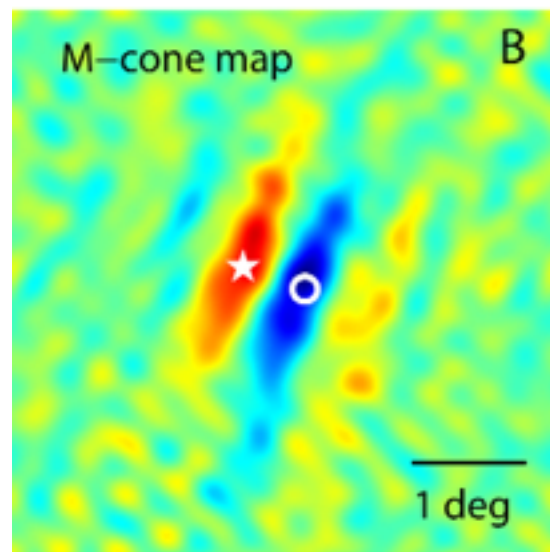
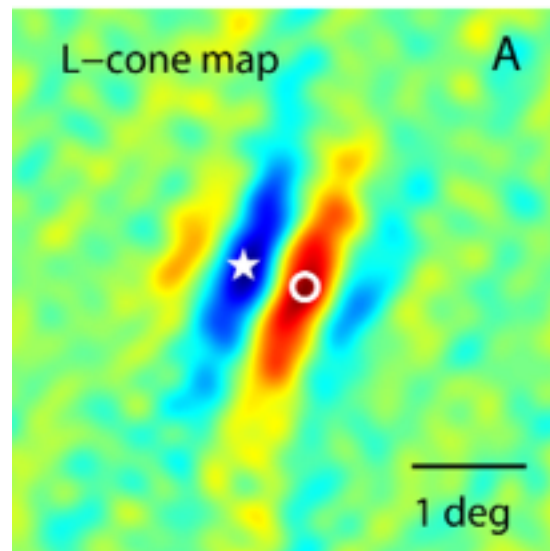


Computational Vision

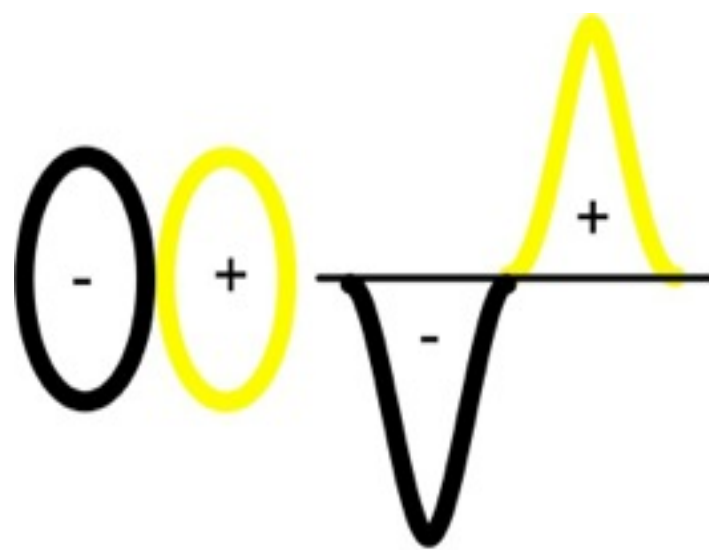
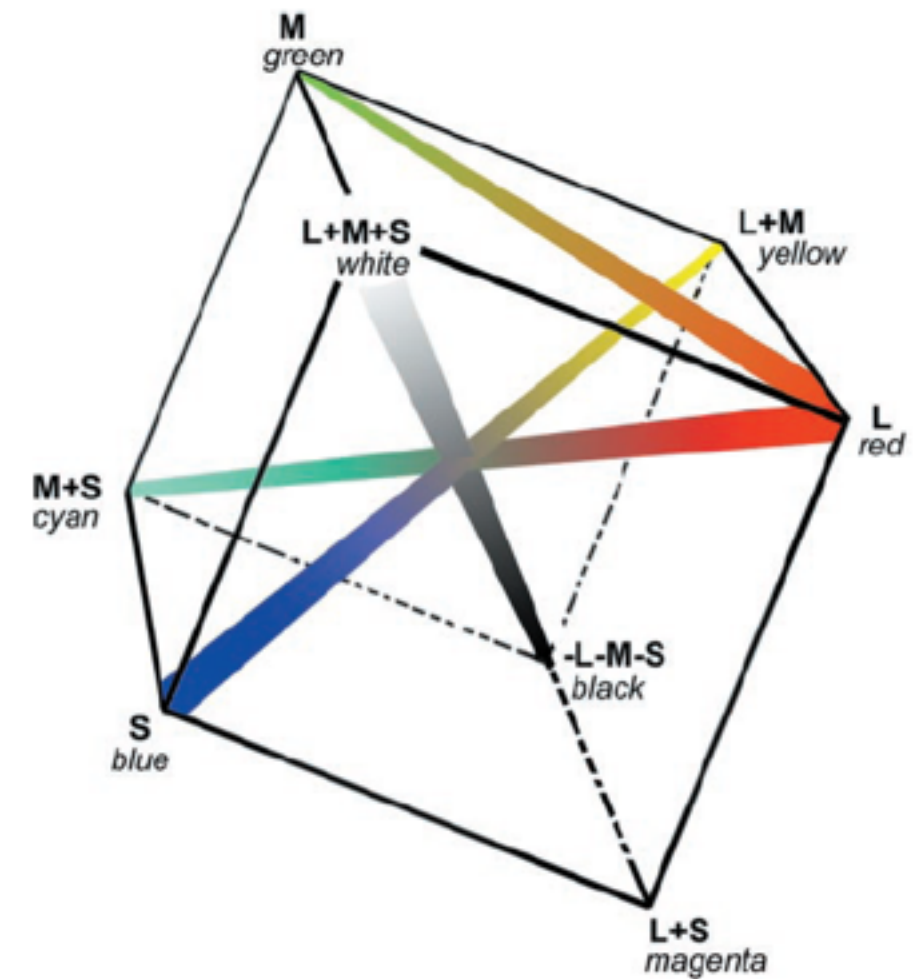
Primary visual cortex

- Orientation selectivity
- Spatial frequency
- **Color opponency**
- Normalization

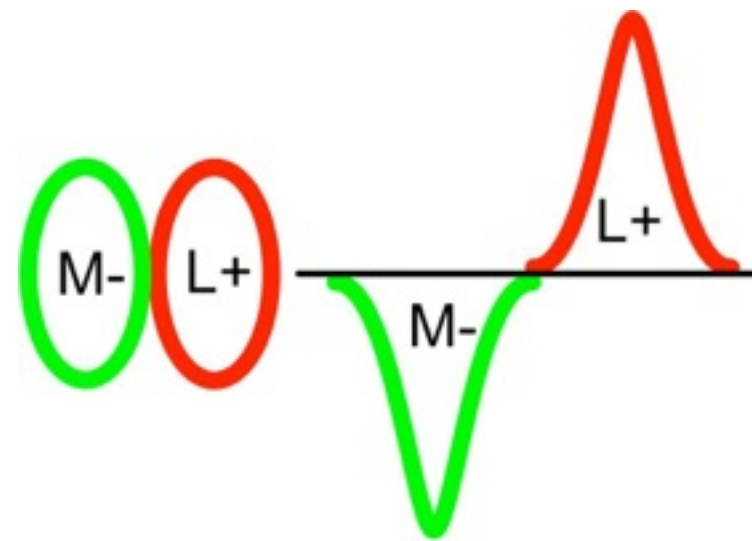




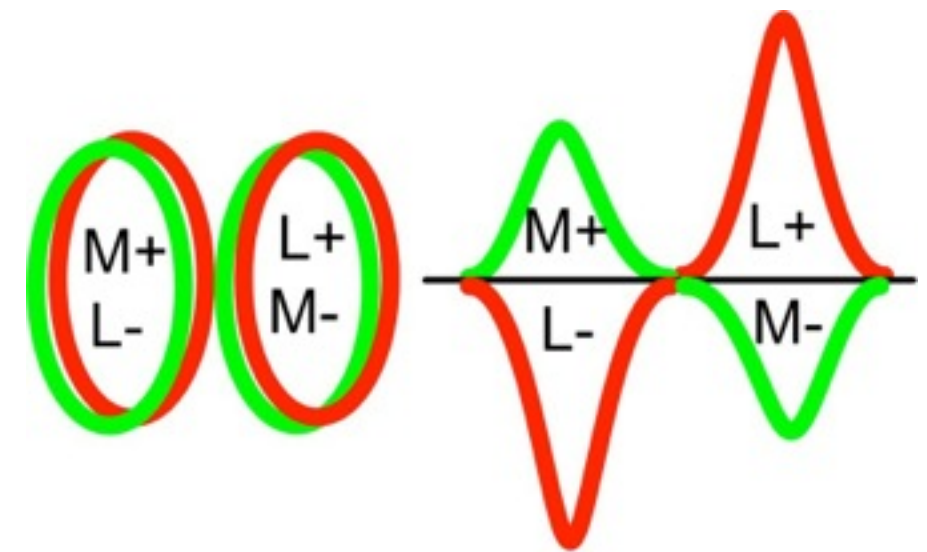
Luminance vs. color selectivity in simple cells



A
Oriented spatial opponent
luminance



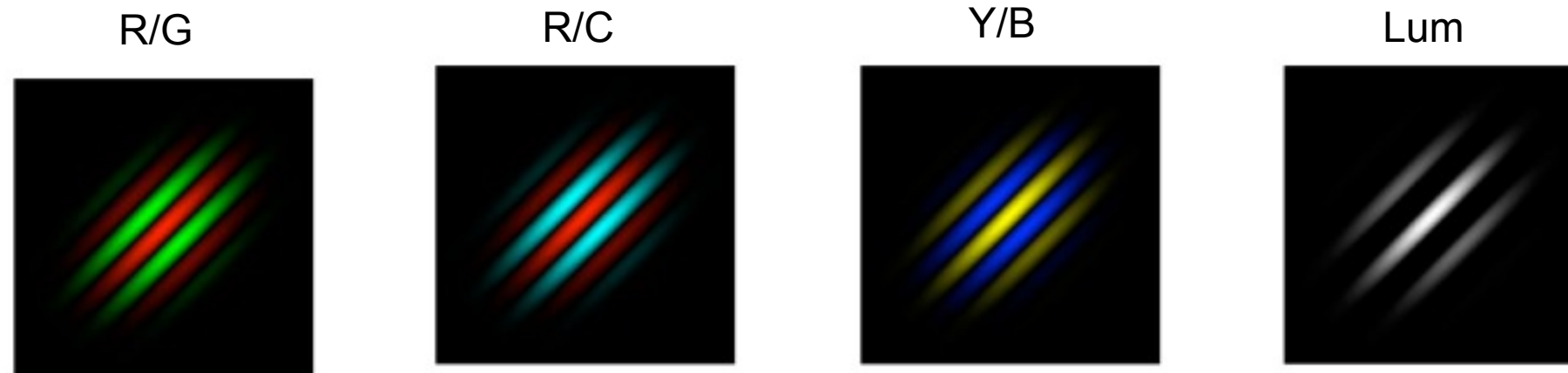
B
Weekly oriented chromatic opponent
Single-Opponency



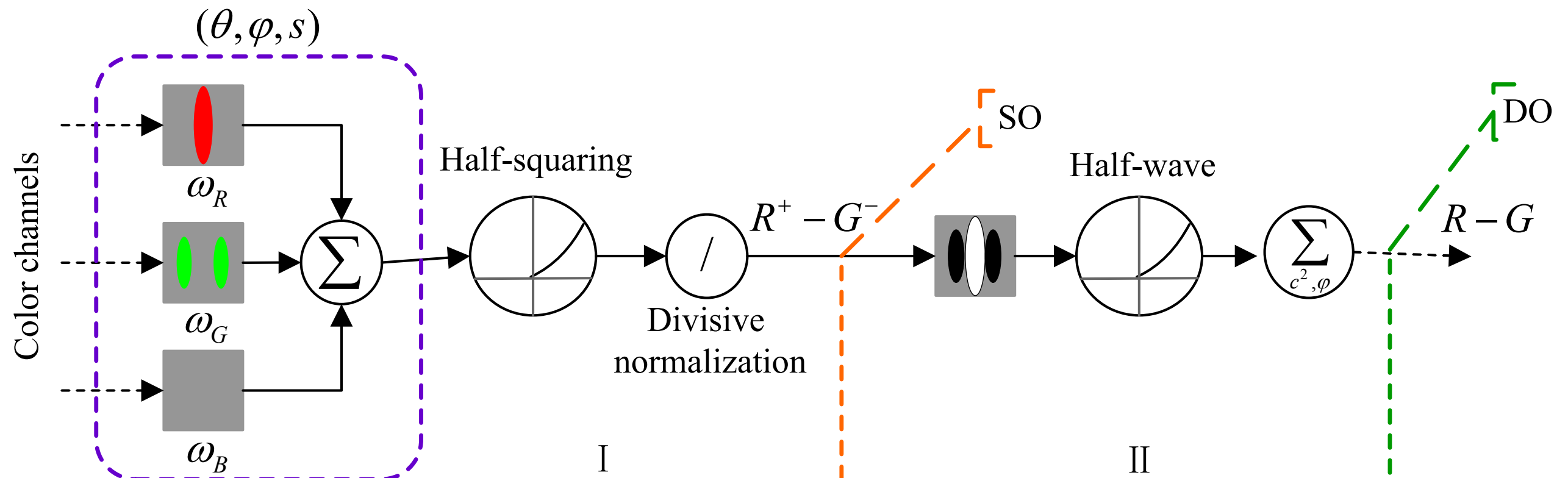
C
Oriented spatio-chromatic opponent
Double-Opponency

Color processing

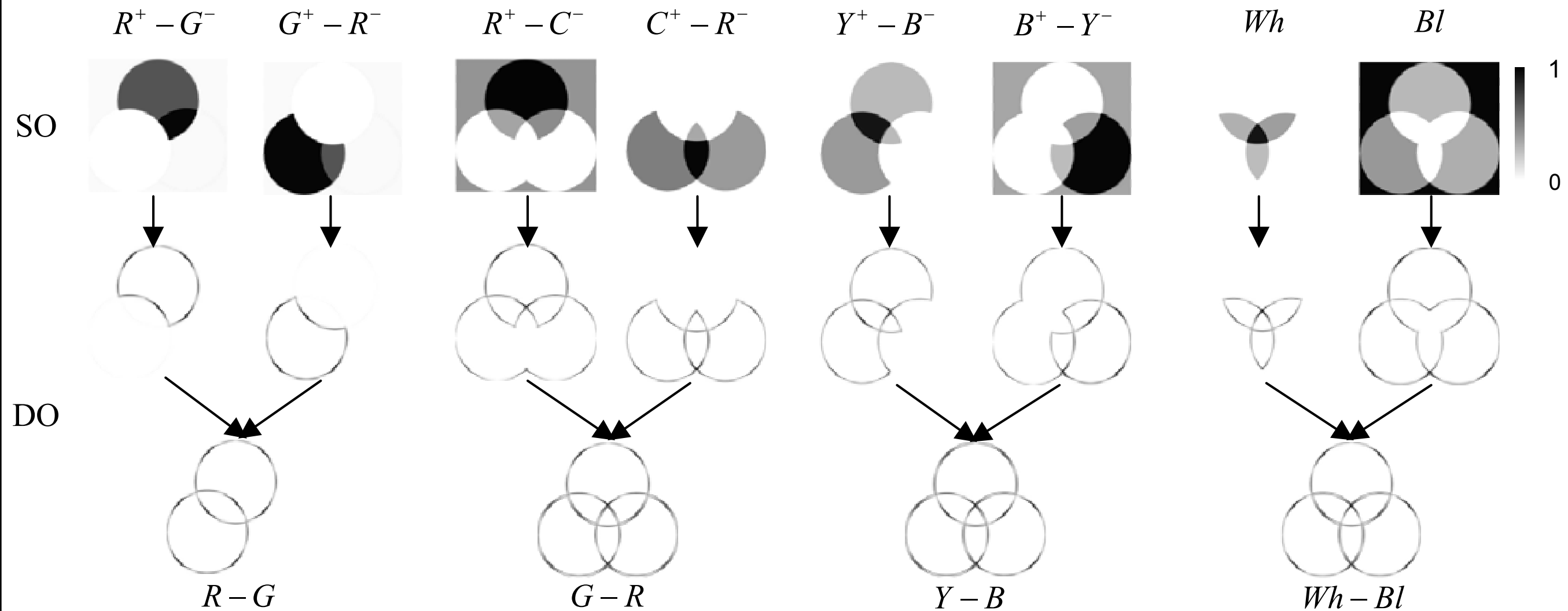
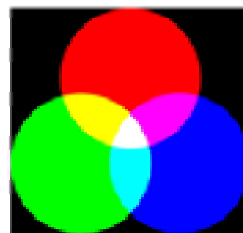
Parameters fitted to
psychophysics data on color
perception



Spatio-chromatic opponent operator



Color processing



Color processing

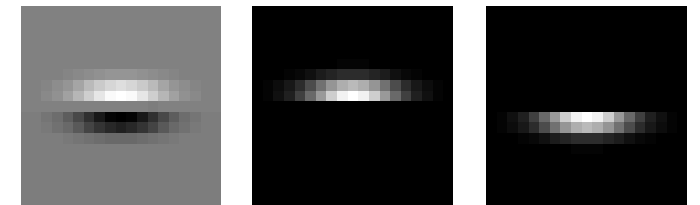
- SO/DO approach improves on all recognition and segmentation datasets tested as compared to existing color representations

• Color datasets

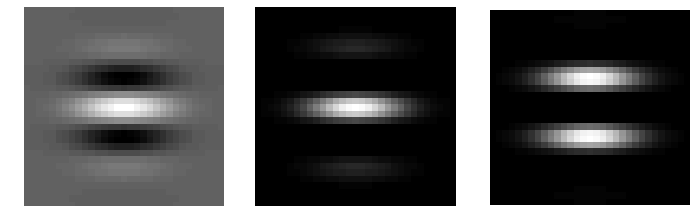
Method	Soccer team			Flower		
	Color	Shape	Both	Color	Shape	Both
Hue/SIFT	69 (67)	43 (43)	73 (73)	58 (40)	65 (65)	77 (79)
Opp/SIFT	69 (65)	43 (43)	74 (72)	57 (39)	65 (65)	74 (79)
SOsIFT/DOsIFT	82	66	83	68	69	79
SOHMAX/DOHMAX	87	76	89	77	73	83

• Pascal challenge

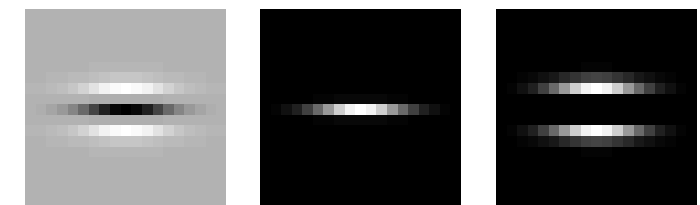
Method	SIFT	HueSIFT	OpponentsSIFT	CSIFT	SODOsIFT	SODOHMAX
AP	40 (38.4)	41	43 (42.5)	43 (44.0)	46.5 (33.3/39.8)	46.8 (30.1/36.4)



A. Gradient used in SIFT



B. Gabor filters used in HMAX



C. Gaussian derivatives used in segmentation

Computational Vision

Primary visual cortex

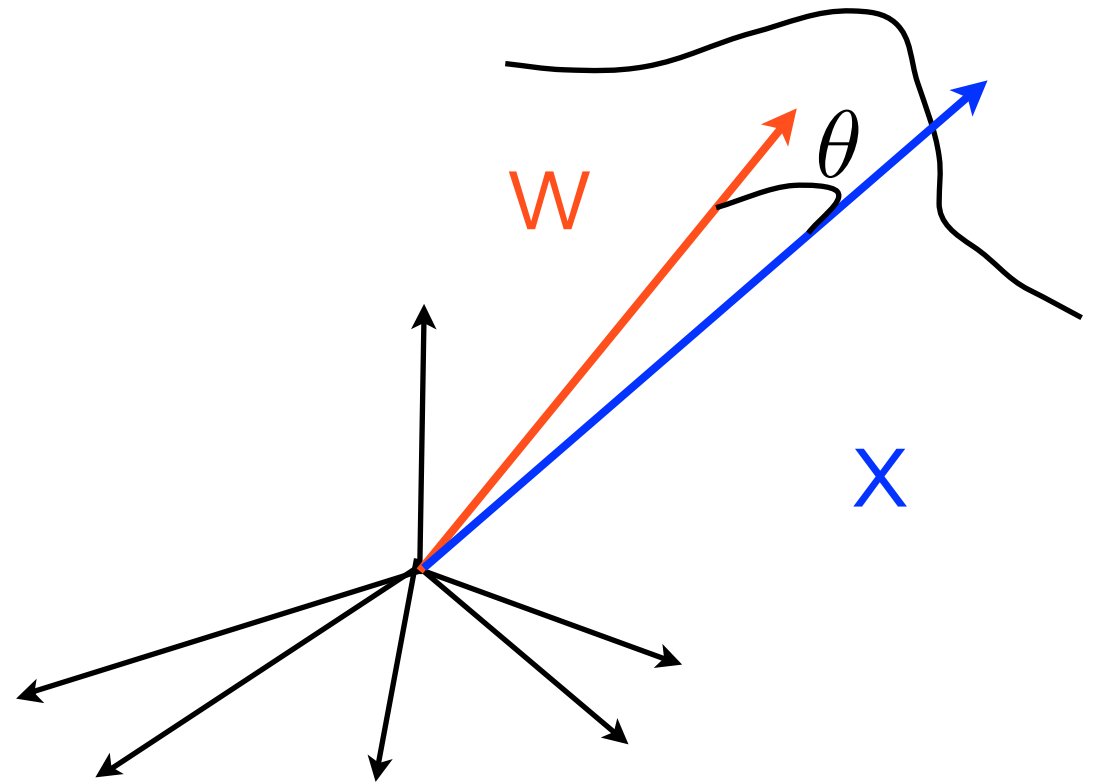
- Orientation selectivity
- Spatial frequency
- Color opponency
- **Normalization**



On the need for normalization circuits

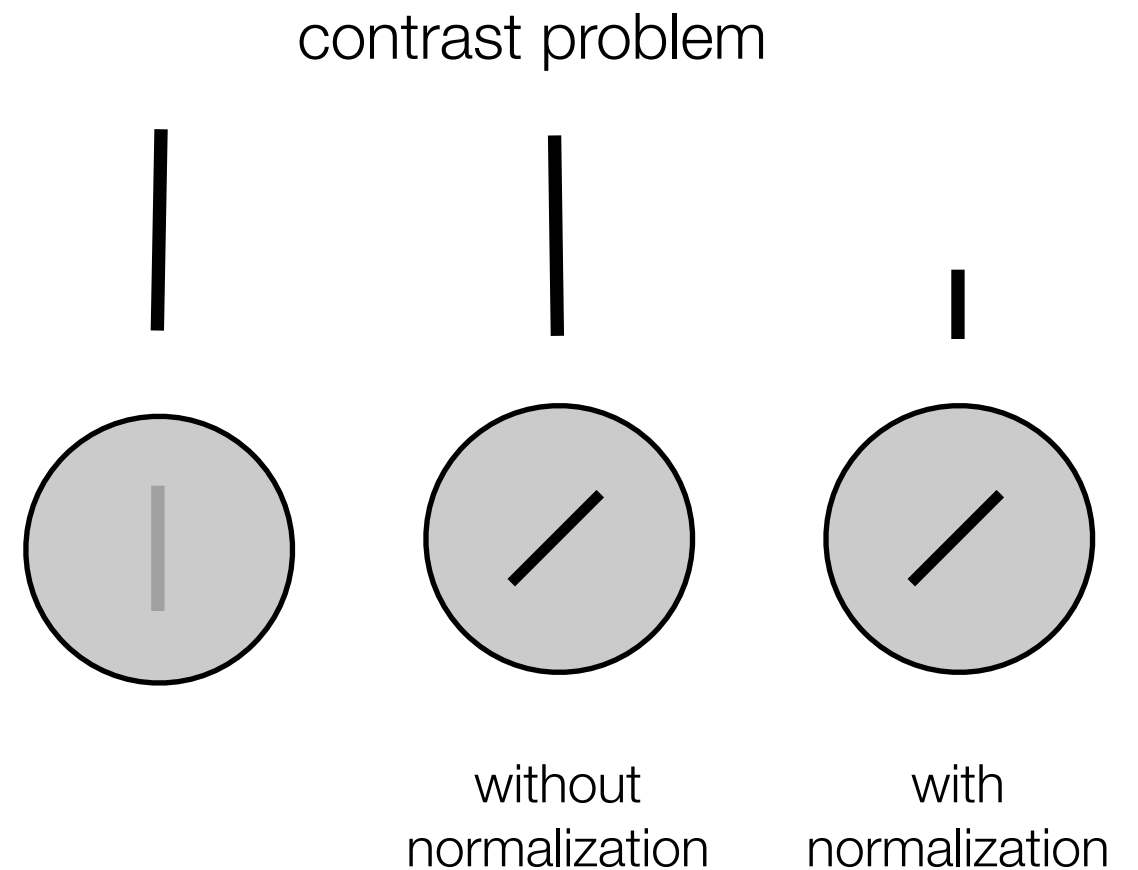
$$\begin{aligned}y(x) &= \sum w_i x_i \\&= \mathbf{w} \cdot \mathbf{x} \\&= ||\mathbf{w}|| ||\mathbf{x}|| \cos(\theta)\end{aligned}$$

$$\begin{aligned}y(x) &= \sum w_i x_i \\&= \frac{\mathbf{w} \cdot \mathbf{x}}{||\mathbf{w}|| ||\mathbf{x}||} \\&= \cos(\theta)\end{aligned}$$

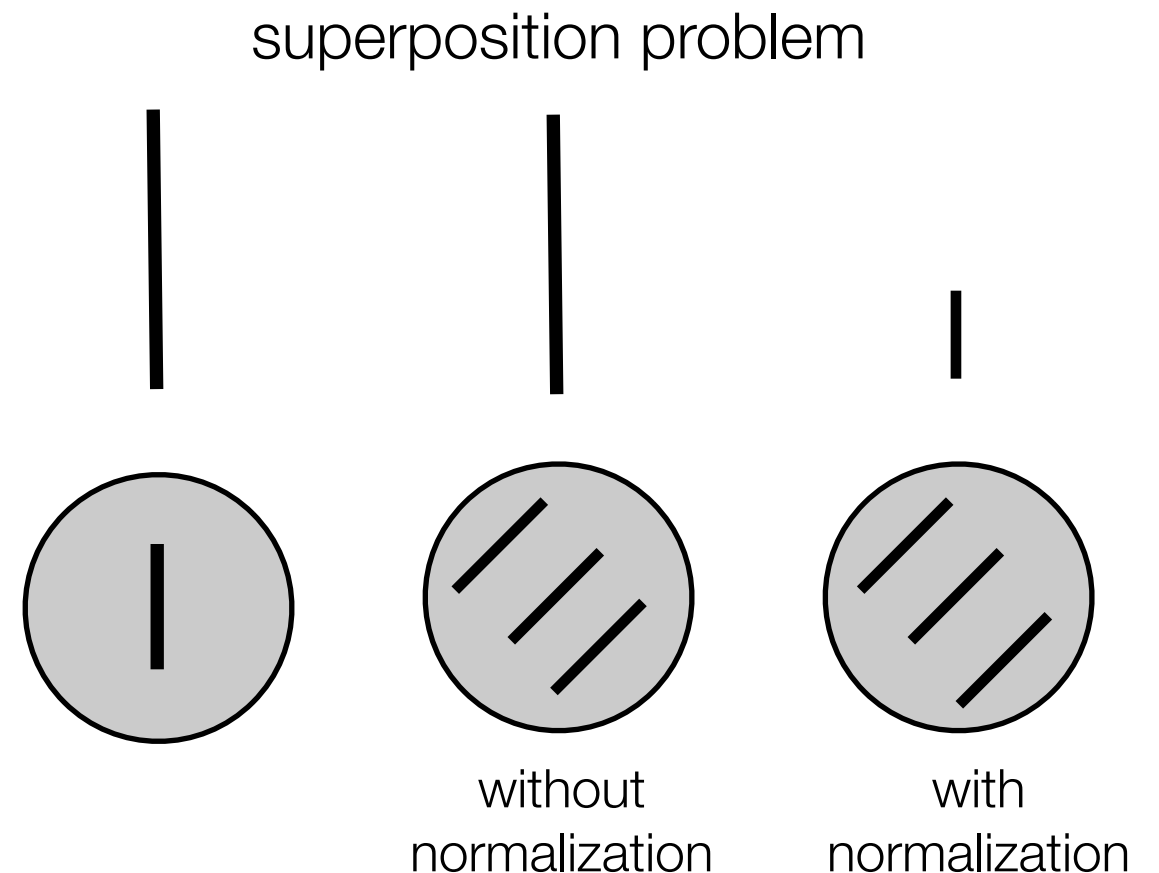


On the need for normalization circuits

$$\begin{aligned}
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 &= \mathbf{w} \cdot \mathbf{x} \\
 &= ||\mathbf{w}|| ||\mathbf{x}|| \cos(\theta)
 \end{aligned}$$



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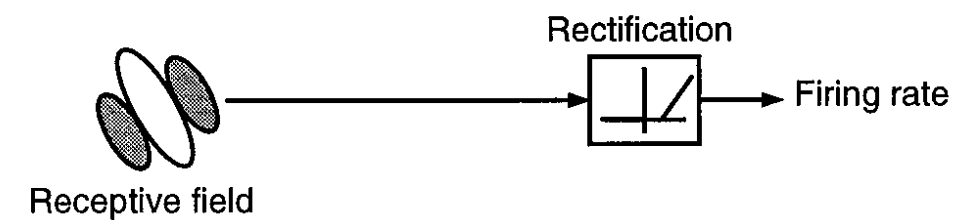


Gain-control circuits

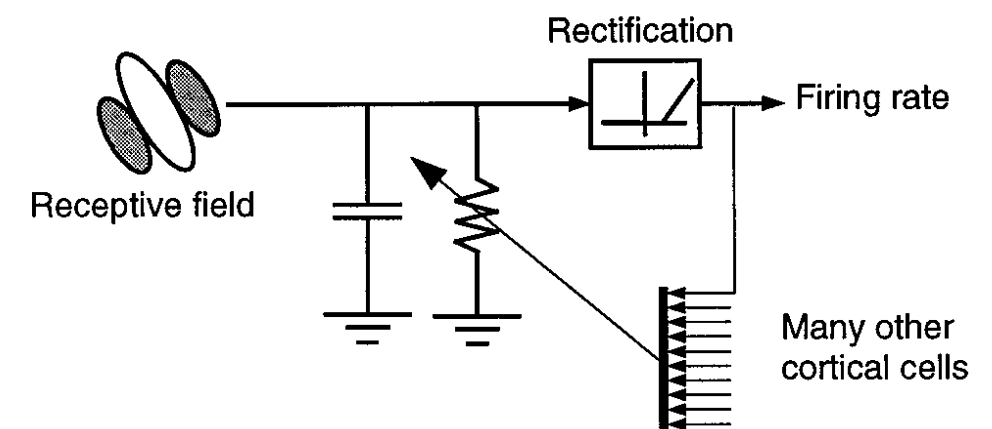
$$y(\mathbf{x}) = \frac{\mathbf{w}^* \cdot \mathbf{x}}{||\mathbf{x}|| + c}$$

$$\begin{aligned} y(\alpha \mathbf{x}) &= \frac{\mathbf{w}^* \cdot \alpha \mathbf{x}}{||\alpha \mathbf{x}|| + c} \\ &= \frac{\alpha \mathbf{w}^* \cdot \mathbf{x}}{\alpha(||\mathbf{x}|| + c/\alpha)} \end{aligned}$$

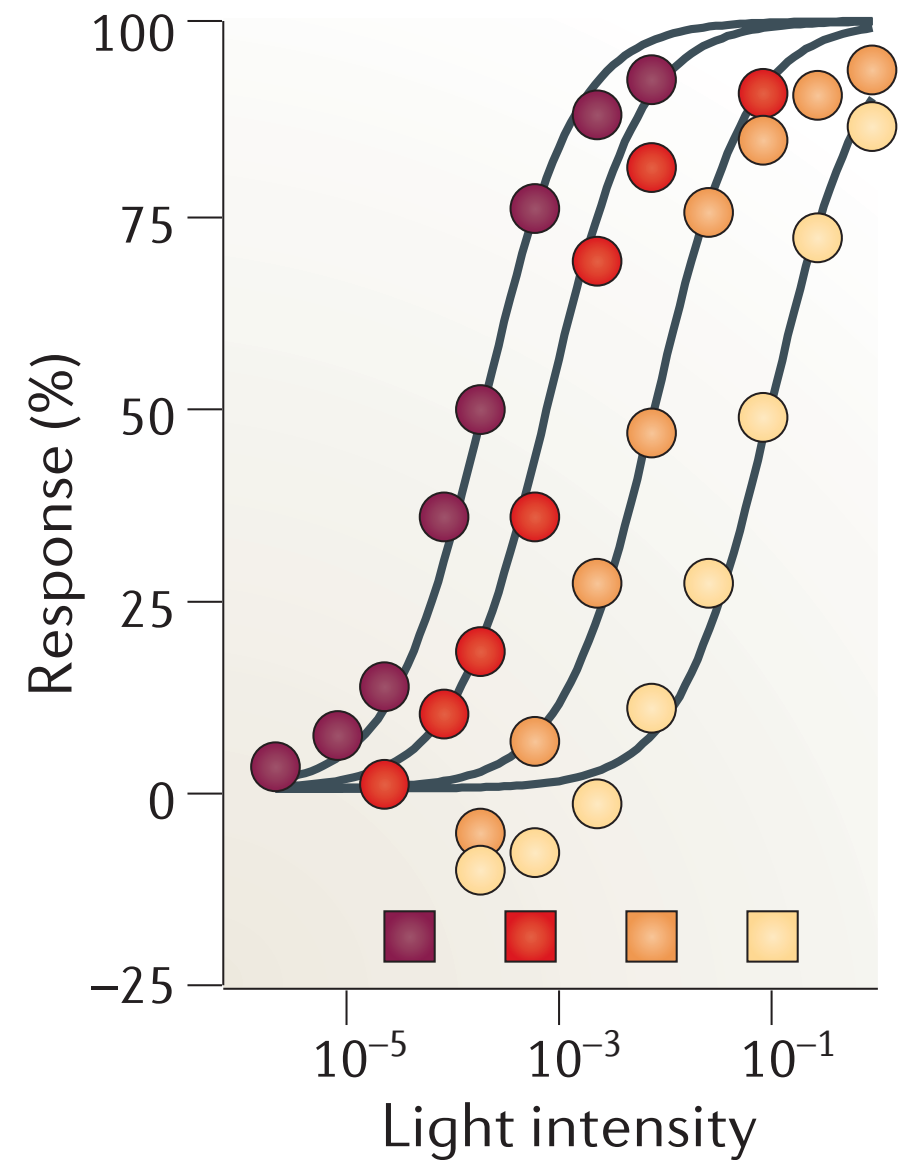
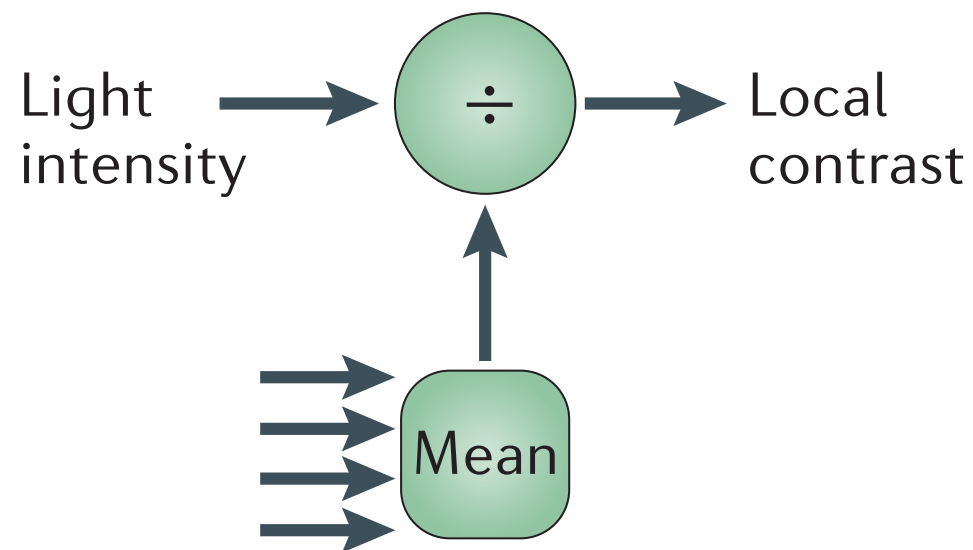
A Linear model



B Normalization model



Gain-control circuits in the (turtle) retina



Gain-control circuits in V1

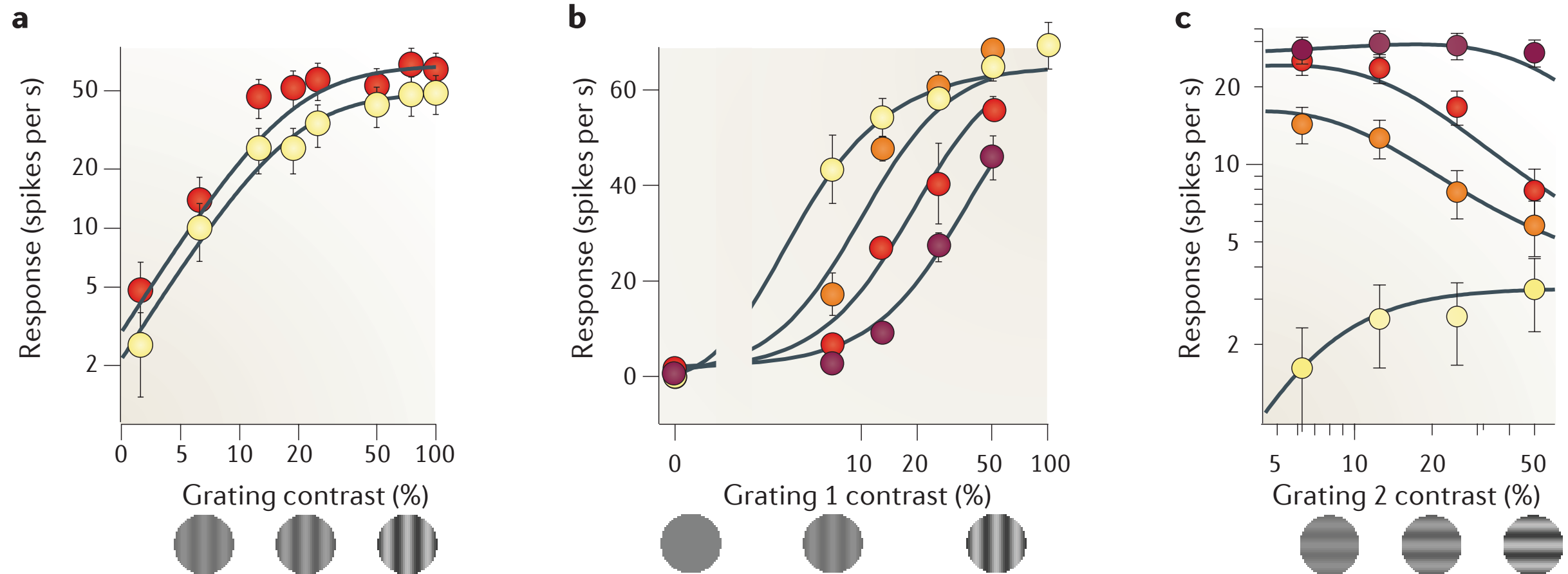


Figure 3 | **Normalization in the primary visual cortex.** **a** | Contrast saturation. Responses as a function of grating contrast for gratings having optimal orientation (shown in red) and suboptimal orientation (shown in yellow). **b** | Cross-orientation suppression. Responses to the sum of a test grating and an orthogonal mask grating (colours indicate mask contrast, from 0% (shown in yellow) to 50% (shown in dark red)). **c** | Transition from drive to suppression. Grating 1 had optimal orientation and grating 2 had suboptimal orientation. Grating 2 could provide some drive to the neuron when presented alone (shown in yellow) but became suppressive when grating 1 had moderate contrasts (shown in red). **d** | Surround suppression. A grating contained in a central disk was surrounded by a grating in an annulus. The annulus elicited minimal responses when presented alone, but suppressed responses to the central disk. **e** | Effects of normalization on population responses. Each dot indicates the response of a population of neurons selective for a given orientation, and each panel indicates the population responses to a stimulus. Stimuli are gratings of increasing contrast, presented alone (top) or together with an orthogonal grating (bottom). Data in part **a** from REF. 43; data in part **b** from REF. 56; data in part **c** from REF. 43; data in part **d** from REF. 142; data in part **e** from REF. 48.

Gain-control circuits in V1

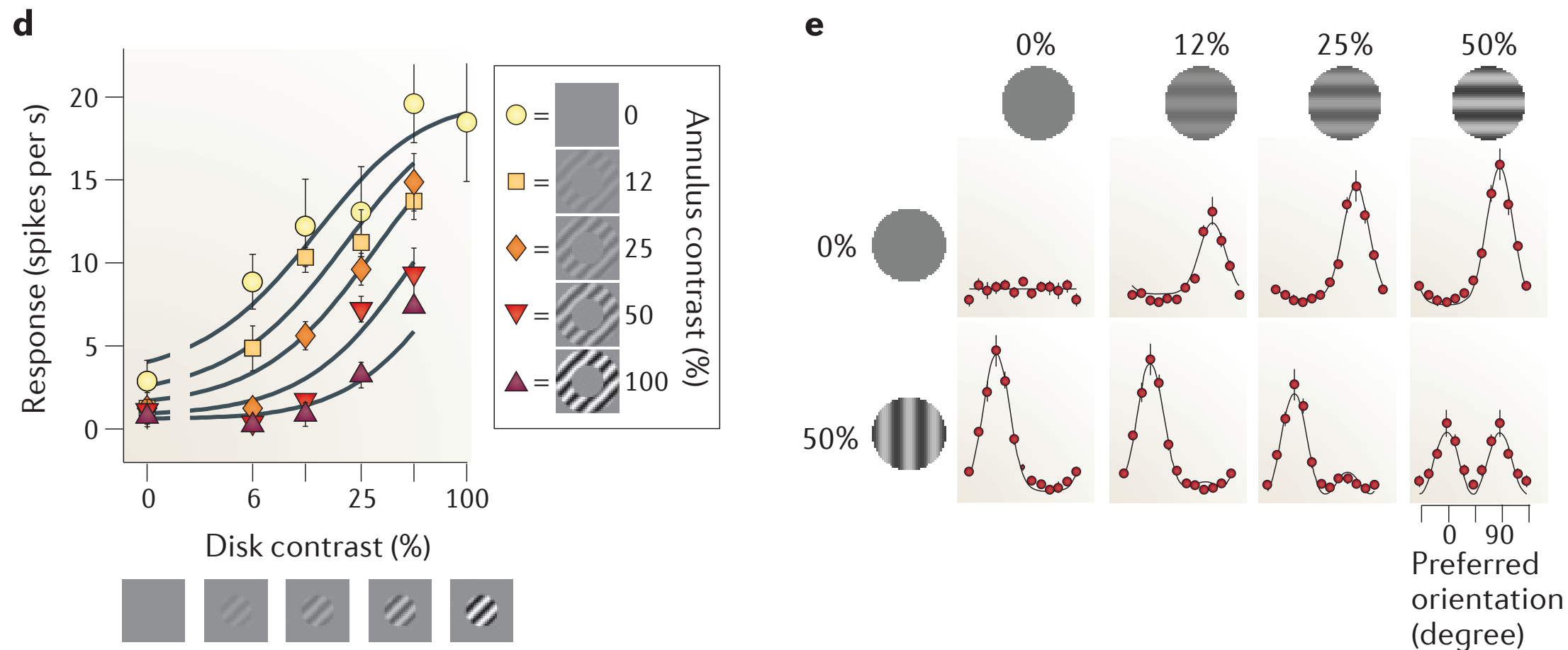


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Gain control circuits in computer vision!

What is the Best Multi-Stage Architecture for Object Recognition?

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- Normalization appears to be the most important component of a good computer vision system (over learning algorithms, architecture, etc)